#### UNIT –I

#### **DEFLECTION OF DETERMINATE BEAMS**

## **Objective:**

To familiarize with the deflection of simple determinate beams.

## Syllabus:

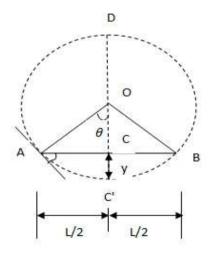
Deflection and slope of a beam subjected to uniform bending moment relation between slope, deflection and radius of curvature & Differential equation for the elastic line of a loaded beam. Determination of slope and deflection for cantilever, Simply Supported beam and over UDL hanging beams subjected to point loads and by Macaulay's and Moment area methods. types of springs in series and parallel-deflection of closely coiled helical springs under axial pull only.

## **Learning Outcomes:**

Student will be able to

- > Determine the slope and deflection for determinate beams using Macaulay's method.
- > Determine the slope and deflection for determinate beams using Moment area method.

#### > Deflection and slope of a beam subjected to uniform bending moment:



A beam AB of length L is subjected to uniform bending moment M.

The initial position of the beam is shown by ACB, where as the deflected position is shown by AC<sup>1</sup> B.

Let R= radius of curvature of the deflected beam

Y= deflection of the beam at the centre

I= Moment of inertia of the beam = slope of the beam at the end A = where is in radius As is slope is Now AC=CB= From the geometry of circle,

The deflection y is a small quantity. Hence the square of a small quantity will be negligible.

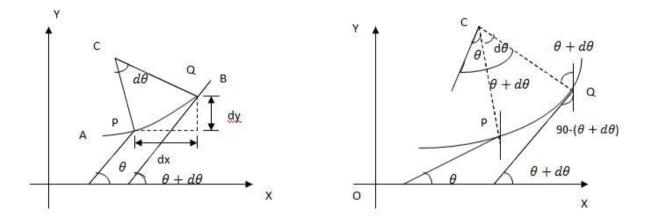
Bending equation = is the central deflection of a beam which bends in a circular arc.

## Slope:

From triangle AOB, sin = = is very small, sin=

#### **Relation between slope, deflection and radius of curvature:**

Let the curve AB represents the deflection of a beam as shown in fig.



Consider a small portion PQ of this beam. Let the tangents at P and Q make angle and with x-axis. Normal at P and Q will meet at C such that PC=QC=R. The point C is known as centre of curvature of the curve PQ. Let the length of PQ is equal to ds. From the geometry of fig R = ds

Differentiate the above equation w.r.t x, we get

M = E.M = EI

Differentiate the above equation w.r.t 's'

If the curvature is very small then is also small and its square is negligible.

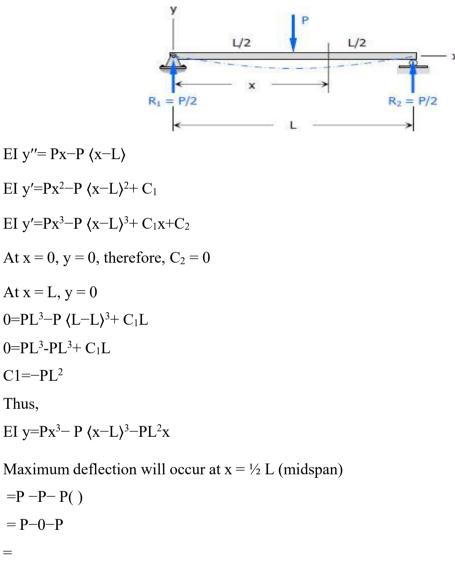
Moment M=EI Shear force F= = EI Rate of loading -w=

- > Various Methods determining Slope and deflection at a section in a loaded beam
  - 1. Double integration method
  - 2. Moment area method

3. Macaulay's method

# **Double integration method:**

Maximum deflection  $\delta$  in a simply supported beam of length L carrying a concentrated load P at midspan.

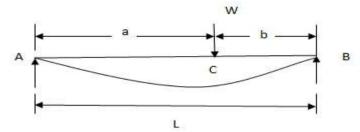


Therefore

# Macaulay's method:

This is a convenient method for determining the slope and deflections of the beam subjected to point loads.

Maximum deflection  $\delta$  in a simply supported beam of length L carrying a eccentric point load P at free end:



The bending moment at any section between A and C at a distance x from A is given by

The bending moment at any section between C and B at a distance x from A is given by

The B.M for all the sections of the beam is expressed in a single equation

we know that M=EI EI integrating the above equation ΕI integrating the above equation EI Apply boundary conditions At x=0, y=0 and At x=L, y=0At x=0 and y=0, then At x=L, y=0, then ) substitute the values of , in the above equation ΕI EI Slope is maximum at A or B at A = At x=0, EI

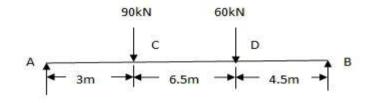
The deflection under the load is , substitute x=a, then we get EI

## **Maximum deflection :**

The slope is zero at the point of maximum deflection,

x= for put the value of x in deflection equation EI

**Example:** Find the deflection of the girder at the points under the loads. and also find the maximum deflection. Take I=64x  $10^{-4}$ m<sup>4</sup> and E=  $2.1 \times 10^{5}$ N/mm<sup>2</sup>.



EI

Integrating on both sides

EI

Again integrating on both sides

### EI

At x=0, y=0 then At x=14, y=0 then Deflection at C, substitute x=3 EI = -2.93mm Deflection at D, substitute x=9.5m = -3.73mm

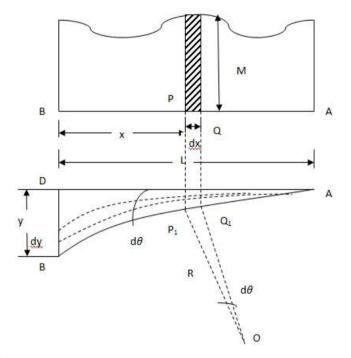
#### **Maximum deflection**

Let us assume that the deflection will be maximum at section between C and D. The slope equation at the section is equal to zero at the maximum deflection.

EI x=6.87m

#### **Moment Area method:**

This method is convenient in case of beam act upon with point loads in which case bending moment area consist of triangles and rectangular. This method is mainly explained by Mohr's theorems.



#### Mohr's theorem 1:

It states that the change of slope between any two points on an elastic curve is equal to area of bending moment diagram between these points divided by flexural rigidity (EI).

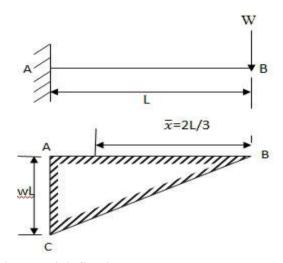
## Mohr's theorem 2:

It states that the intercept taken on a vertical reference line of tangents at any two points on an elastic curve is equal to the moment of the bending moment diagram between these points above the line divided by flexural rigidity.

Deflection and slope of a cantilever by Moment area method:

## Cantilever carrying a point load at the free end:

The fig shows a cantilever of length L fixed at end A and free at the end B.It carries a point load W at B.



At the fixed end A, the slope and deflection are zero. Then according to moment area method,

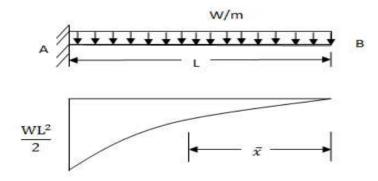
C

And

A= Area of B.M diagram between A and B = = Distance of C.G of area of B.M diagram from B=

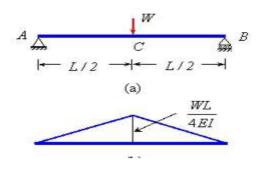
# Cantilever carrying a uniformly distributed load:

The fig shows a cantilever of length L fixed at end A and free at the end B. It carries a uniformly distributed load of w/unit length over the entire length.



Determine the end slope and deflection of the simply supported beam carrying a point

load at the centre:



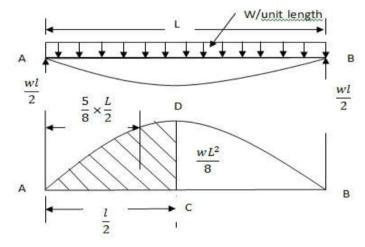
Slope at A

But area of B.M diagram between A and C = Area of triangle ACD

=

=

Determine the end slope and deflection of the simply supported beam carrying a uniformly distributed load at the centre:



But area of B.M diagram between A and C = Area of parabola ACD

=

=

**Example:** Find the slope and deflection of cantilever beam at the free end using moment area

method.

to find the area of the B.M diagram, divide the fig into two triangles and one rectangle.

area  $A_1$ = area  $A_2$ == area  $A_3$ = Total area of B.M diagram,  $A = A_1 + A_2 + A_3$ =

=0.005 radians

++=

 $= 7 \times 10^{13} \text{Nmm}^3$ 

# **Close-Coiled Helical Spring**

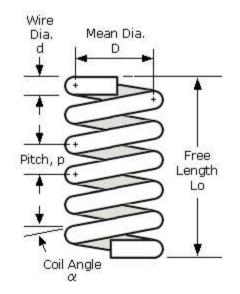
## **Axial Load:**

a) Neglecting curvature and direct shear effects:

Consider a Closely coiled helical spring as shown in fig. under the action of axial load.

С

Let,



W = Axial Load

D = Mean coil diameter

d = Dia. of Spring wire

 $\delta$  = Axial deflection

G = Modulus of rigidity

 $\Theta$  = Angular Deflection

n = No. of active coils

= Maximum shearing stress induced

The following assumptions are made:

- i. An element of an axially loaded helical spring behaves essentially as a straight bar in pure torsion.
- ii. The planes perpendicular to the bar axis do not wrap or distort during deformation. As a result of this the shearing stress will have a linear distribution along the radius.

Fig. Shows the circular sectional element of the spring wire under torsion. Torque on the spring acting about the axis of the spring.

At any radius x from the center 'O' of the wire, the shearing stress is,

The torque dT taken up by a ring of width dr at a radius r will be,

Total torque T =

-----(1)

Calculate rotation and deflection of the spring, consider the elementary angle  $d\Theta$  through which one cross section rotates w.r.t other.

$$\Theta = -----(2)$$

From eq (1) & (2)

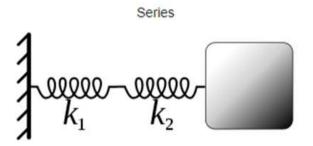
Now,

```
deflection \delta = \Theta =
Stiffness, K = =
Direct Shear Stress,
Therefore, Maximum resultant shear stress = +
```

**Springs in Series**: when two springs of different stiffness are joined end to end to carry a common load w, they are said to be connected in series, as shown in fig

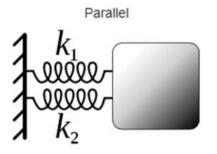
Total deflection,

Now,



Where K is the combined stiffness

**Springs in parallel**: when two springs are joined in such a way that they have a common deflection, they are said to be connected in parallel two different.



&  $\Theta =$ 

W=W1+W2

# <u>UNIT-1</u>

## Assignment-Cum-Tutorial Questions

# A. Questions testing the remembering / understanding level of students

## I) Objective Questions

- 1. Slope at a point in a beam is the
  - (a) Vertical displacement (b) Angular displacement (c) Horizontal displacement (d) None
- 2. Deflection at a point in a beam is the
  - (a) Vertical displacement (b) Angular displacement (c) Horizontal displacement (d) None
- 3. Maximum deflection in a S.S. beam with W at centre will be
  - (a)  $WL^{3}/36EI$  (b)  $WL^{3}/24EI$  (c)  $WL^{3}/48EI$  (d)  $WL^{3}/96EI$
- 4. Maximum slope in a S.S. beam with W at center will be
  - (a) At the supports (b) At the center
    - (c) In between the support and the center (d) None
- 5. Maximum deflection in a cantilever beam with UDL 'w' over the entire span will be (a) At the left hand support (b) At the Right support (c) At the center (d) None
- 6. Deflection under the load in a S.S.beam with 'W' not at the center will be
  (a) 4Wa<sup>2</sup>b<sup>2</sup>/3EIL
  (b) 2Wa<sup>2</sup>b<sup>2</sup>/3EIL
  (c) Wa<sup>2</sup>b<sup>2</sup>/3EIL
  (d) None
- 7. Distance of maximum deflection from the center in a S.S.Beam with 'W' not at the center will be

- (a)  $[2 (L^2 b^2)/3]^{0.5}$  (b)  $[(L^2 b^2)/3]^{0.5}$ (c)  $[(3L^2 - b^2)/3]^{0.5}$  (d)  $[4(L^2 - b^2)/3]^{0.5}$
- 8. Difference in slopes between two points A and B by the moment area method is given by
  - (a) Area of BMD between A and B/2EI (b) Area of BMD between A and B/3EI
  - (c) Area of BMD between A and B/EI (d) Area of BMD between A and B/4EI
- 9. Difference in deflections between two points A and B by the moment area method is given by
  - (a) (Area of BMD between A and B). /2EI
  - (b) (Area of BMD between A and B). /3EI
  - (c) (Area of BMD between A and B). /EI
  - (d) None

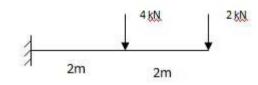
- 10. Macaulay's method is more convenient for beams carrying
  (a) Multi concentrated loads
  (b) Multi number of UDL
  (c) Multi-concentrated and multi UDL loads
  (d) None
- 11. The ratio of maximum deflections of a cantilever beam of span L with (i) a load W at free end (ii) a U.D.L over entire length of total W is given by
  - (a) 3/8 (b) 8/3 (c) 5/8 (d) 8/5
- 12. If the depth of a cantilever is doubled and width is halved, the deflection of a cantilever due to a point load at free end changes in the ratio.
  - (a) 1/2 (b) 1/4 (c) 1/8 (d) 1/16

## II) Problems:

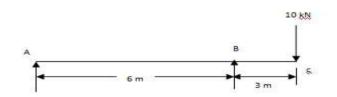
- 1. A beam of length 4.8 m and of uniform rectangular section is simply supported at its ends. It carries a uniformly distributed load of 10 kN/m run over the entire length. Calculate the width and depth of the beam if permissible bending stress is 7 N/mm<sup>2</sup> and maximum deflection is not to exceed 0.95 cm. Take E for beam material =  $1.05 \times 10^4 \text{ N/mm}^2$ .
- 2. A simply supported beam of 4 m span carries a UDL of 20 kN/m on the whole span and in addition carries a point load of 40 kN at the centre of span. Calculate the slope at the ends and the maximum deflection of the beam. Take  $E = 200 \text{ GN/m}^2$  and  $I = 5000 \text{ cm}^4$ .
- 3. A cantilever 3 m long is of rectangular section 120 mm wide and 240 mm deep it carries a UDL of 2.5 kN per meter length for a length of 1.5 m from the fixed end and a point load of 1 kN at the free end. Find the deflection at the free end. Take E = 10 GN/ m<sup>2</sup>.
- 4. A cantilever 3m long carries two point loads, 60 kN each, at distance of 0.75 m and 1.75 m respectively from the fixed end. Determine the deflection at the free end. Take  $E=200GN/m^2$  and I=12689400 cm<sup>4</sup>.
- 5. A steel girder of uniform section, 14 meters long, is simply supported at its ends. It carries concentrated loads of 120 kN and 80 kN at two points 3 meters and 4.5meters from the two ends respectively. (a) Calculate the deflection of the girder at the two

points under the two loads.(b) The maximum deflection. Use Macaulay's Method. Take:  $I = 16 \times 10^4 \text{ m}^4$ , and  $E = 210 \times 10^6 \text{ KN/m}^2$ .

- A simply supported beam of span 10m is loaded with a UDL of 5000 N/m over a length of 3 m from the left end. Find the maximum deflection of the beam. Take E = 0.2 MN/mm<sup>2</sup> and I= 3000 cm<sup>4</sup>.
- The cantilever beam shown in Fig. has a rectangular cross-section 50 mm wide by h mm high. Find the height h if the maximum deflection is not to exceed 10 mm. Use E = 10 GPa.



- A girder rests on two supports 5m apart, and carries a load of 60 kN, 2 m from one support. Find the ratio of maximum deflection to deflection under the load.
- 9. A simply supported beam is 6 m long and has flexural rigidity of 3 MNm<sup>2</sup>. It a carries a point load of 400 N at the middle and a UDL of 200 N/m along its entire length. Calculate slope at the ends and deflection at the middle. Prove that the relation
- 10. An overhanging beam ABC is loaded as shown in fig. Find the slopes over each support and at the right end. Find also the maximum deflection between the supports and the deflection at the right end. Take  $E= 2 \times 10^5 \text{ N/mm}^2$  and  $I= 5 \times 10^8 \text{ mm}^4$



- 11. A simply supported beam, having rectangular cross-section, carries a concentrate load at the centre of span. If the maximum flexural stress is 9 N/mm<sup>2</sup>, find the depth of section to the span ratio in order the central deflection may not exceed 1/480 of span.
- 12. A close helical spring 10cm mean diameter is made of 20 turns of 1 cm dia steel rod. The spring carries an axial load of 100N.find the shearing stress developed in the spring and the deflection of the load .assume modulus of rigidity 84Gpa.
- 13. A close-coiled helical spring is having a stiffness of 1kN/m of compression under a

maximum load of 4.5 N and a maximum shearing stress of 45 Mpa. The solid length of the spring (i.e. when the coils are touching) is to be 4.5 cm. Find the diameter of the wire and the mean diameter of the coils required. Consider G as 42 Gpa

- 14. a) A close-coiled helical spring made of 12 mm round steel has 12 coils and the mean diameter of the coils is 16 cm. The spring is subjected to an axial load of 150 N. Determine the elongation, intensity of tensional stress and strain energy per cubic metre under the loaded condition. G=84 Gpa.
  - b) If the axial load is removed and an axial torque of 10 N-m is applied, determine the axial twist, intensity of bending stress, and work stored per cubic meter in the spring. E=210 GPa.

# UNIT-II COLUMNS AND STRUTS

# **Objective:**

To get familiarize with different types of columns To Analyze the crippling loads for columns for different support end conditions To Analyze the struts for UDL and point loads.

# Syllabus:

Introduction – Types of columns - Short, medium and long columns-Axially loaded compression members-crushing load- Euler's theorem for long columns-assumptions-derivation of Euler's critical load formula-various end conditions-equivalent length of column-slenderness ratio-Euler's critical stress-limitations of Euler's theory.

#### Learning outcome:

## Student will be able to

Gain knowledge on different types of columns

Analyze and to determine the Crippling loads by using Euler's formula and Rankine's formula Determine the Bending moments and stresses due to lateral loading on struts.

## **COLUMN:**

Column is a vertical structural member, which is subjected to axial compressive load. It transmits the load from roof slab and beam, including its self weight to the foundation.

## **STRUT:**

A structural member which carries an axial compressive load in roof truss is called as strut. It may be horizontal, inclined or even vertical

## **TYPES OF COLUMNS:**

#### Short columns:

Columns which failed due to crushing and its slenderness ratio is less than 12 called short columns. Generally short columns are failed due to crushing loads.

### Long columns:

Columns which failed due to buckling and having slenderness ratio greater than 12 are called Long columns.

## **Euler's Theory**

Assumptions in Euler's Theory

- 1. Initially the column is perfectly straight and the load is applied axially
- 2. The cross section of column is uniform throughout its length.
- 3. The column material is perfectly elastic, homogeneous and isotropic and thus obeys Hooke's law.
- 4. The length of the column is very large as compared to the cross-section dimensions
- 5. Direct stress is neglected.
- 6. The failure of column occurs due to buckling alone.

End conditions of column

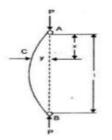
- 1. Both ends hinged
- 2. Both ends fixed
- 3. One end is fixed and other hinged
- 4. One end is fixed and other free

Note: for fixed end, the slope and deflection is zero and for hinged end, the deflection is zero

# Derivation of Crippling loads for different end conditions:

## • Column hinged at both ends

Consider a column carrying an axial compressive load P and having both ends hinged as shown in fig.



Taking origin at A, the bending moment at a distance x is we know that

Let

General solution is

, where A and B are constants

End conditions are a) b)

At  $\Rightarrow A=0$ 

At =>

Now B = 0 or

if B = 0 the y = 0 and the column will remain straight, which is not ture

Therefore

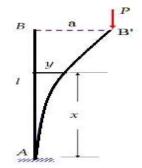
; n= 0, 1, 2, 3.....

Taking fundamental value i.e., n=1

This load is known as the critical load and is denoted by Pcr and is also called as Euler's load

• Columns with one end is fixed and other free

Consider a column AB of length 1 fixed at A and free at B carrying a load P at B. as a result of loading the column deflect into a curved form such that the free end B deflects through 'a' and occupies a new position B<sub>1</sub>.



Now consider any section at a distance x from A Let y= deflection at the column at section Moment  $M_x = P(a-y)$ 

Let

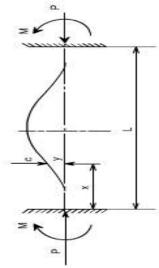
General solution is , where A and B are constants End conditions are a) b) c) At => A= -aAt => Bk = 0Either B = 0 or k = 0 Since the load is not equal to zero. Therefore B = 0

At =>

# • Columns with both ends fixed

Consider a column AB of length l fixed at both of its ends and carrying a critical load at B.

Now consider any section at a distance x from A



Let y= deflection at the column at section

Since both ends of the column are fixed and it is carrying a load, therefore there will be same fixed end moments at A & B.

Let M<sub>o</sub>=FEM at A& B

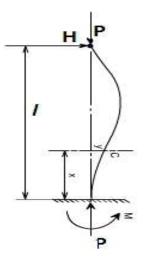
Let

General solution is , where A and B are constants End conditions are a) b) c) At  $\Rightarrow$  A = -At  $\Rightarrow$  Bk = 0

B=0

At =>

• Column with one end is fixed and other end is hinged



Let

General solution is , where A and B are constants End conditions are a) b) At => A =At => Bk - = 0B= At =>

c)

S.NO	END CONDITIONS	RELATION BETWEEN EFFECTIVE AND ACTUAL LENGTHS	CRIPPLING LOAD $P_E = (\pi^2 EI) / L_e^2$
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1	Both sides hinged	L <sub>e</sub> =L	$P_{E} = (\pi^{2}E I) / L^{2}$
2	One fixed and other free	L <sub>e</sub> =2L	$P_{\rm E} = (\pi^2 {\rm EI}) / 4 {\rm L}^2$
3	both fixed	$L_e = L/2$	$P_E = 4(\pi^2 EI) / L^2$
4	One fixed and other hinged	$L_e = L/\sqrt{2}$	$P_{E}=2(\pi^{2}EI)/L_{e}^{2}$

# • Slenderness ratio:

Euler's formula for the crippling load

$$P_E =$$

We know that the buckling of a column under the crippling load will take place about the axis of least moment of resistance. Subjected to I=A

A is the area, K is the least radius of gyration

 $P_E =$ 

Where is known as slenderness ratio.

Slenderness ratio is defined as ratio of equivalent length of column to the least radius of gyration of the section.

## • Euler's critical stress:

Euler's formulae for the crippling load  $P_E =$ Euler's critical stress

## • Limitations of Euler's formula:

Euler's critical stress

For a column both ends hinged,  $L_e = l$ 

Crippling stress become as Euler's critical stress , where is slenderness ratio.

If the slenderness ratio is small the crippling stress will be high. But for column material the crippling stress can't be greater than the crushing stress. Hence, when the slenderness ratio is less than a certain limit, Euler's formula gives a value of crippling stress greater than the crushing stress. In the limiting case we can find the value of *l*/k for which crippling stress is equal to crushing stress.

For example: A mild steel column with both ends hinged

Crushing stress =330N/mm<sup>2</sup>

 $E=2.1x10^{5}N/mm^{2}$ 

Equating the crippling stress to the crushing stress =330

Hence, if the slenderness ratio is less than 80 for mild steel column with both ends hinged, then Euler's formula will not be valid.

## • Rankine's formula:

The empirical formula given by Rankine is given by

Where P= crippling load by Rankine's formula

=crushing load =

= crushing load =

Where I=A

Crippling load

## • Long columns subjected to eccentric loading:

When a column is subjected to an eccentric load the maximum intensity of compressive stress is given by

= =

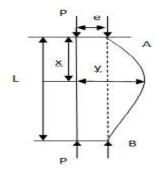
 $\mathbf{P} =$ 

When the effect of buckling is also included, then

P=

# > Column subjected to eccentric loading with both ends are hinged:

Consider a column hinged at both ends and subjected to an eccentric load P as shown in fig.



At a distance x from A,

General solution is y=A coskx +B sinkx x=0, y=e then A=e x=l, y=e then e= e coskl + B sinkl.

Y= At x=, deflection is maximum

Now

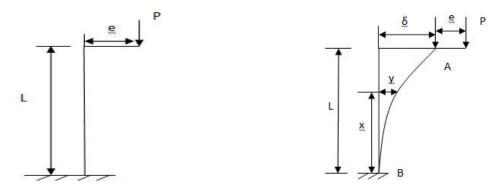
Resultant stress becomes

= distance of the outermost fiber in compression from the N.A

For other end conditions,

# > Column subjected to eccentric loading one end fixed other end free:

When a column is subjected to an eccentric load P at eccentricity e. let us assume that top of the column is free and the bottom of the column is fixed.



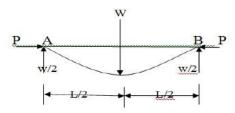
The max bending moment for the column at B and is equal to P M= P.e.seck l=Pesecl For maximum compressive stress

=

If both ends are hinged, then

• Strut pinned at both ends and subjected to an axial thrust P and a transverse point load W at the center:

Consider any section at a distance x from A



General solution is y=A coskx + B sinkx -

x=0, y=0 then A=0

X=, then

Y= -

## Maximum deflection:

At x=, y=

# Maximum bending moment:

Substitute maximum deflection in above equation, then

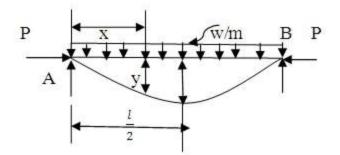
Tan= When is small Tan=

# Maximum stress:

Stress due to bending, =

• Strut subjected to an compressive axial thrust P and a transverse u.d.l w per unit length of both ends are pinned:

Consider any section at a distance x from A



Differentiate the above equation is w.r.t x,

Again differentiate the above equation is w.r.t x

Solution for the above equation is M =A coskx +B sinkx+ x=0, y=0 then A== X=,

B= M=coskx sinkx+

Maximum bending moment: At X= = coskx sinkx+

**Maximum deflection:** at X=, y=, M= Maximum stress:

## UNIT – III

## **INDETERMINACY - PROPPED CANTILEVERS**

## **Objective:**

To learn the concept of Static and kinematic indeterminacy and analyse the propped cantilevers.

#### Syllabus:

Degree of static and kinematic indeterminacy- analysis of propped cantilevers for concentrated loads and UDL-shear force and bending moment diagrams

## **Learning Outcomes:**

After completion of this unit the student will be able to

- 1. Distinguish between static and kinematic indeterminacy.
- 2. Evaluate prop reaction, shear force and bending moment for propped cantilever beam
- 3. Draw the shear force and bending moment diagrams for different conditions for propped cantilever and fixed beams

#### **Learning Material**

## Introduction:

Structure is an assemblage of a number of components like slabs, beams, columns, walls, foundations and so on, which remains in equilibrium.

When any elastic body is subjected to a system of loads and deformation takes place and resistance is setup against the deformation, then the elastic body is known as Structures. If no resistance is setup in the body against deformation, it is known as an unstable structure or mechanism.

## **Classification of structures:**

## a) Based on type of joints:

- **Pin jointed frames:** Members are connected by means of pin joints. These frames support the loads by developing only axial forces.
- **Rigid Jointed frames:** These frames resist external forces by developing bending moments, shear forces, axial forces and twisting moments in the members of the frame.

## b) Based on Dimensions:

- **Plane frames:** All members of the plane frame as well as external loads are assumed to be in one plane.
- **Space frames:** All members do not lie in one plane. Very often, it is also a combination of series of frames.

## c) Based on static equilibrium conditions:

## • Determinate Structures:

Determinate structures are analyzed just by the use of basic equilibrium equations. By this analysis, the unknown reactions are found for the further determination of stresses.

Examples of determinate structures are: cantilever beams, three hinged arches etc.

# • Indeterminate Structures:

Redundant or indeterminate structures are not capable of being analyzed by means of use of basic equilibrium equations. Along with the basic equilibrium equations, some extra conditions are required to be used like compatibility conditions of deformations etc to get the unknown reactions for drawing bending moment and shear force diagrams.

Examples of indeterminate structures are: Propped cantilever, fixed beams, continuous beams, fixed arches, two hinged arches, portals, multi-storeyed frames, etc.

Special methods like strain energy method, slope deflection method, moment distribution method, column analogy method, virtual work method, matrix methods, etc are used for the analysis of redundant structures.

#### **Static Indeterminacy**

The number of equations required over and above the equations of static equilibrium to find the unknown reactions is known as degree of static indeterminacy or degree of redundancy of the structure.

 $\mathbf{D}_{\mathrm{S}} = \mathbf{D}_{\mathrm{se}} + \mathbf{D}_{\mathrm{si}}$ 

 $\mathbf{D}_{se} = External \ indeterminacy$ 

= r-6 (for space fame)

= r-3 (for plane fame)

Here r indicates number of reactions

D<sub>si</sub> = Internal Indeterminacy

= m-(2j-3), for pin jointed plane frame

= m-(3j-6), for pin jointed space frame

= 3C, for rigid jointed plane frame

= 6C, for rigid jointed space frame

Here j indicates number of joints.

C indicates number of closed loops.

## **Kinematic Indeterminacy**

It is defined as the number of independent components of joint displacements with respect to a specified set of axes. It is also called as degrees of freedom.

For beams the reactions	and degree of	of freedom at an	n ends are as follows,

Support Type	Image	Reactions	r	D.O.F
Roller		1	<i>r</i> =1	2
Pin		$\rightarrow$	r=2	1
Fixed		さ	<i>r</i> =3	0

#### For pin jointed frames

 $\mathbf{D}_{\mathbf{k}} = 2\mathbf{j} - \mathbf{r}$  (for plane frames)

 $\mathbf{D}_{\mathbf{k}} = 3\mathbf{j} - \mathbf{r}$  (for space frames)

 $D_k$  – Degree of kinematic indeterminacy

- j-Number of joints
- r-Number of reactions

## For rigid jointed frames

 $\mathbf{D}_{\mathbf{k}} = 3\mathbf{j} - \mathbf{r}$  (for plane frames considering axial strains)

Dk = 3j - (m+r), (for plane frames neglecting axial strains)

 $\mathbf{D}_{\mathbf{k}} = 6\mathbf{j} - \mathbf{r}$  (for space frames considering axial strains)

Dk = 6j - (m+r) (for space frames neglecting axial strains)

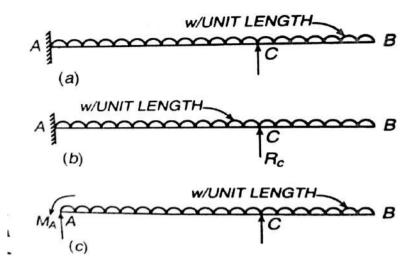
D<sub>k</sub> – Degree of kinematic indeterminacy

- j-Number of joints
- r-number of reactions
- m-number of members.

#### **Propped Cantilever**

A cantilever supported at any point in the beam is called as a Propped Cantilever. When a cantilever is supported at any point in the span, the structure becomes indeterminate. Under vertical load, there will be two unknown reactions at the fixed end and one at supported end. Two equations of statics i.e.  $\sum V = 0$  and  $\sum M = 0$  are available. This type of structure cannot be analysed by the equations of the statics. One more equation besides two equations of statics is required to solve three unknowns. Therefore, this structure is said to be indeterminate to first degree. The third equation can be obtained by considering the deflections or slopes.

Statically indeterminate structures can be analysed by using method of consistent deformation and moment area method.



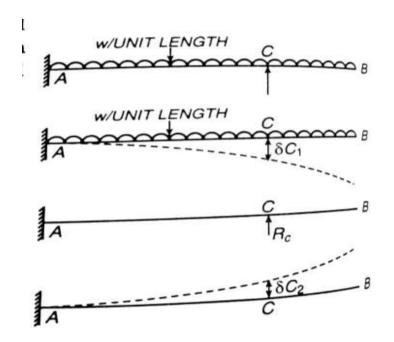
#### Method of consistent deformation

#### Step-1

- 1. In the first step the support at C is removed and the deflection at C is calculated. Let it be  $\Delta c_{1.}$
- 2. The loading is removed and force  $R_c$  equal to unknown reaction at C, is applied at C and the deflection at C is worked out. Let the deflection be  $\Delta c_2$ . Then

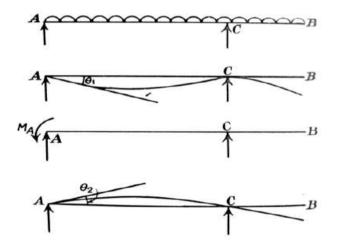
 $\Delta c_1 + \Delta c_2 = 0$  in case the support C remain at the same level when the beam is loaded.  $\Delta c_1 + \Delta c_2 = \Delta$  in case the support C sinks by  $\Delta$ .

3. By using the above two equations the unknown reaction R<sub>c</sub> can be obtained and the structure can be analyzed.



### Step-2

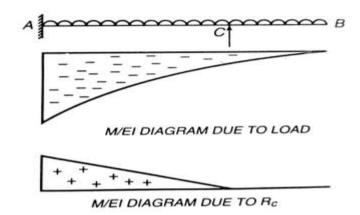
- 1. The structure is made determinate by removing fixity at A and thus the structure will be a simply supported beam with overhang.
- 2. Under external loading the slope at A is worked out. Let the slope be  $\theta_1$ .
- 3. The load is removed and a moment  $M_A$  equal to fixed end moment is applied at A. Let this slope be  $\Theta_2$ . Then
  - $\Theta_1 + \Theta_2 = 0$ , in case there is no rotation of supports.
  - $\theta_1 + \theta_2 = \theta$ , in case the support rotates by  $\theta$ .
- 4. By using the above equation the value of unknown moment  $M_A$  can be calculated.



#### **Moment Area Method**

#### Step-1 (Taking R<sub>c</sub> as indeterminate reaction)

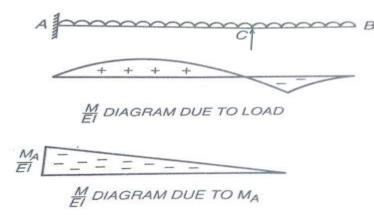
1. The bending moment diagrams due to external loading and  $R_c$  are drawn considering ABC as a cantilever.



2. As the fixed end A is fixed, the tangent to the deflection curve at A will pass through C in case A and C are at the same level. Thus the moment of M/EI diagram between A and C about C will be zero. If there is change of level equal to  $\Delta$  between A and C the moment of M/EI diagram between A and C will be - $\Delta$ .

#### Step-2 (Taking M<sub>A</sub> as indeterminate moment)

1. The bending moment diagrams are drawn for the load and fixed end moment  $M_A$  considering ABC as simply supported beam with overhang.



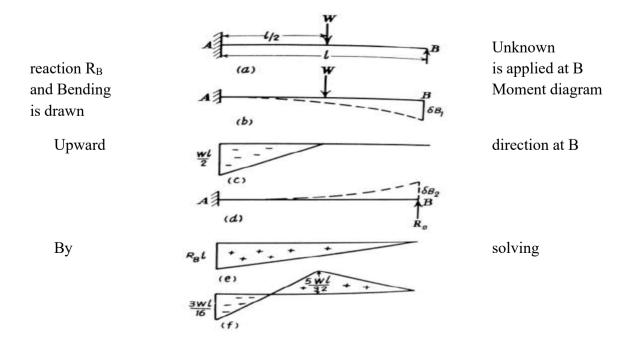
- 2. In case A and C are the same level, the moment of M/EI diagram between A and C about C will be zero.
- 3. If there is change of level  $\Delta$  between the supports A and C after loading, the moment of M/EI diagrams between A and C about C will be - $\Delta$ .

#### Problems

1. Draw B.M diagram for the propped cantilever subjected to point load, as shown in the figure. The support A & B remain at the same level after loading.

Sol: The support at B is removed and the B.M diagram for the cantilever is drawn as shown in fig C

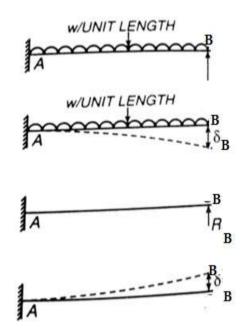
The deflection  $\Delta_{B1}$  at B will be equal to the moment of M/EI diagram about B.



Maximum +VeB.M will be at the centre and is equal to 5WL/32.

2. Determine the reaction components for the propped cantilever subjected to UDL as shown in figure.

Sol: To analyse this propped cantilever method of consistent deformation is used and the deflection criteria is considered.



Remove the support at B as shown in the figure.

Step 1: Let be the deflection at point B due to external loading.

According to Moment area theorem 2

= Moment of area of M/EI diagram between A& B about B.

 $= Wl^{4}/8EI$ 

Step 2: Remove the external loading and introduce unknown reaction .

 $R_B$  = Propped reaction at point B as shown in fig C.

Let be the deflection at point B due to  $R_B$ .

Then according to moment area theorem

 $= R_B l^3/3EI$ 

Since the supports are at the same level even after loading =

 $R_{\rm B}\!=\!3WL/8.$ 

# UNIT-IV

# **FIXED BEAMS**

## **Objective:**

To get familiarize with different types of fixed beams To Analyze the loads for different beams

# Syllabus:

Analysis of fixed beams for concentrated loads and UDL- SFD and BMD with and without sinking of supports.

Learning outcome:

### Student will be able to

Analyze the fixed beams with and without sinking of supports.

## **Fixed Beams**

# Introduction

A fixed or a build in beam has both of its ends rigidly fixed so that the slope at the ends remains zero. Such a beam is also called as the encaste beam. The fixed ends give rise to fixing moments there in addition to the reactions. If perfect end fixing can be achieved, build in beams carry smaller maximum bending moments and have smaller deflections that the corresponding simply supported beams with the same loads applied. Therefore they are stronger and stiffer. However the need for high accuracy in aligning the supports and fixing the ends during erection increases the cost. Small subsidence of either support or temperature changes can set up large stresses. The end fixings are also normally sensitive to vibrations and fluctuations in bending moments.

There are four unknown reaction components. Two at end A i.e.,  $R_A \& M_A$  and two at end B i.e  $R_B \& M_B$ . But the available equilibrium equations are two only i.e.,  $\sum V = 0$  and  $\sum M = 0$ .

Fixed beam is a statically indeterminate structure and its degree of indeterminacy is 2.

So we need two more equations to analyse the fixed beam.

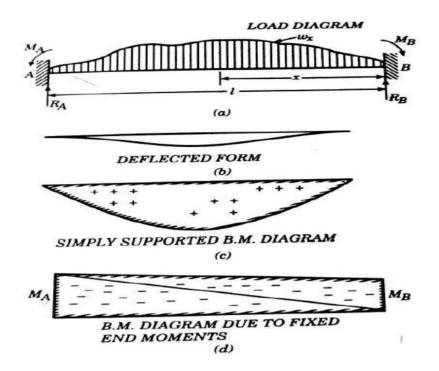


Fig (a) shows fixed beam AB of uniform section and span 1 loaded as shown in the figure. As the ends of the beam are fixed, the slope at support will be shown in fig (b). Let  $M_A$  and  $M_B$  be the fixed end moments at supports A & B respectively. The angle between the tangents drawn on the deflected curve is equal to zero. The area of M/EI diagram between A & B is Zero.

The fixed beam can be taken as simply supported beam with end moments  $M_A \& M_B$  such that the slopes at the supports are zero. Due to simply supported condition the loading will cause +ve B.M. the B.M will vary from  $M_A$  at A to  $M_B$  B. So the area of M/EI diagram due to fixed end moments is equal to area of M/EI diagram due to simply supported beam.

Let  $A_s$  be the area of B.M considering beam as simply supported and  $A_i$  be the area of the B.M due to fixed end moments.

 $A_i = A_s$ 

.....(1)

The intercept made by the tangents drawn at A & B will be zero. Therefore moment of area of M/EI diagram between A & B about B will be zero. Similarly, moment of area of M/EI diagram between A & B about B will be zero.

Ax/EI = 0

Here x is the distance of the C.G of B.M diagram area from the support.

 $X_s$  = distance of C.G of  $A_s$  from end A

 $X_i$  = distance of C.G of  $A_i$  from end A.

By substituting the values we finally get

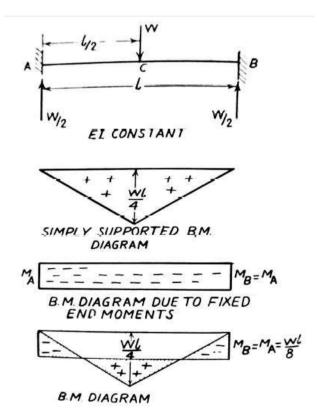
......(2)

From equations 1& 2 the values of and  $M_B$  can be found out.

#### Calculation of fixed end moments for a fixed beam of uniform section.

Case 1: Concentrated load at the centre of span.

A fixed beam can be treated as a simply supported beam with end moments  $M_A \& M_B$ . So that the slope at the supports is zero.



Simply supported bending moment diagram is a triangle and bending moment diagram due to fixed end moments is a rectangle.

Since the beam is symmetrical  $M_A = M_B$ 

We have  $A_s + A_i = 0$ 

(
$$M_{\rm A} = M_{\rm B} = {\rm WL}/8$$

To find the point of contra flexure equate  $M_x$  to Zero.

Point of contra flexure occurs at L/4 from either end.

Maximum +ve B.M occurs at the centre & is equal to WL/8

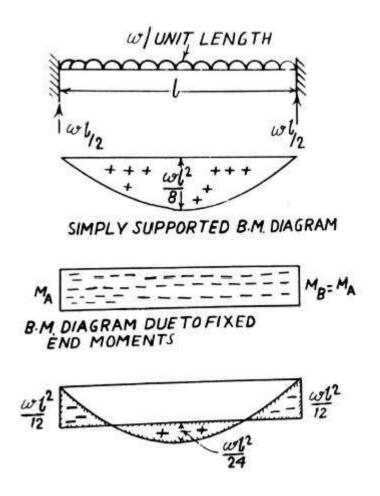
Maximum – Ve B.M occurs at the supports & is equal to -WL/8.

### Case :2

UDL throughout the span.

A fixed beam can be treated as a simply supported beam with end moments  $M_A \& M_B$ . So that the slope at the supports is zero.

Simply supported bending moment diagram is a triangle and bending moment diagram due to fixed end moments is a rectangle.



Since the beam is symmetrical  $M_A = M_B$ 

We have  $A_s + A_i = 0$ 

 $M_B = W l^2 / 12 = M_{A.}$ 

Point of contraflexure occurs at a distance of 0.212L from either ends.

Maximum +VeB.M occurs at the centre & is equal to  $Wl^2/24$ 

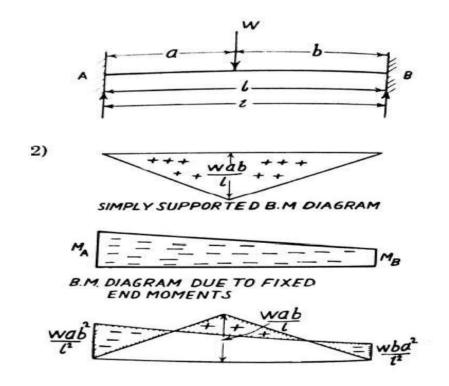
Maximum -VeB.M occurs at the supports & is equal to  $Wl^2/12$ .

Case 3:

### **Unsymmetrical Concentrated Load.**

A fixed beam can be treated as a simply supported beam with end moments  $M_A \& M_B$ . So that the slope at the supports is zero.

Simply supported bending moment diagram is a triangle and bending moment diagram due to fixed end moments is a rectangle.



 $R_A = Wb/l$  &  $R_B = Wa/l$ 

Maximum B.M for simply supported beam = Wab/l

We have a relation

.....(1)

.....(2)

From relation (1)

.....(3)

From relation (2)

.....(4)

Solving equations 3 & 4

$$\begin{split} M_B &= Wa^2 b/l^2 \\ M_A &= Wab^2/l^2 \end{split}$$

Point of contra flexure occurs at a distance of **ab/l** from either ends.

#### UNIT – V

#### **CONTINOUS BEAMS – THEOREM OF THREE MOMENTS**

A continuous beam is a statically indeterminate multispan beam on hinged support. The end spans may be cantilever, may be freely supported or fixed supported. At least one of the supports of a continuous beam must be able to develop a reaction along the beam axis

#### **Objectives:**

Derive the Clapeyron's theorem of three moments Analyze continuous beam with different moment of in- ertia with unyielding supports Analyze the continuous beam with different moment of inertia in different spans along with support settlements using three moment equation.

### 11.1 INTRODUCTION

A beam is generally supported on a hinge at one end and a roller bearing at the other end. The reactions are determined by using static equilibrium equations. Such as beam is a statically determinate structure. If the ends of the beam are restrained/clamped/encastre/fixed then the moments are included at the ends by these restraints and these moments make the structural element to be a statically indeterminate structure or a redundant structure. These restraints make the slopes at the ends zero and hence in a fixed beam, the deflection and slopes are zero at the supports.

A continuous beam is one having more than one span and it is carried by several supports (minimum of three supports). Continuous beams are widely used in bridge construction. Consider a three bay of a building which carries the loads  $W_1$ ,  $W_2$  and  $W_3$  in two ways.

FIG. 11a Simply supported beam

FIG. 11b Bending moment diagrams

A

R

D

#### FIG. 11c Continuous beam

C

FIG. 11d Bending moment diagram

If the load is carried by the first case then the reactions of individual beams can be obtained by equilibrium equations alone. The beam deflects in the respective span and does not depend on the influence of adjacent spans.

In the second case, the equilibrium equations alone would not be sufficient to determine the end moments. The slope at an interior support B must be same on either side of the support. The magnitude of the slope can be influenced by not only the load on the spans either side of it but the entire loads on the span of the continuous beam. The redundants could be the reactions or the bending moments over the support. Clapeyron (1857) obtained the compatibility equation in term of the end slopes of the adjacent spans. This equation is called theorem of three moments which contain three of the unknowns. It gives the relationship between the loading and the moments over three adjacent supports at the same level.

#### 11.2 DERIVATION OF CLAPEYRON'S THEOREM (THEOREM OF THREE MOMENTS)

Figure 11e shows two adjacent spans *AB* and *BC* of a continuous beam with two spans. The settlement of the supports are  $\Delta_A$ ,  $\Delta_B$  and  $\Delta_C$  and the deflected shape of the beam is shown in  $A^{j}B^{j}C^{j}$  (Fig. 11f).

A

*В* FIG. 11e С

The primary structure is consisting of simply supported beams with imaginery hinges over each support (Fig 11g). Fig 11h shows the simply beam bending moment diagrams and Fig 11i shows the support moment diagram for the supports.

A compatibility equation is derived based on the fact that the end slopes of adjacent spans are equal in magnitude but opposite in sign. Using Fig 11f and the property similar triangles  $\Delta_B - \Delta_A + \delta^B \qquad \Delta_C - \Delta_B + \delta^B$ 

$$\frac{B - \Delta_A + \delta^{B^-}}{GD} = \frac{\Delta_C - \Delta_B + \delta^B}{CF}$$
$$\frac{\Delta_C - \Delta_B + \delta^B}{CF}$$
$$DB_j = B_j F$$

\_\_\_\_

$$\begin{array}{cccc} l_1 & l_2 \\ \delta_B & \delta_B & \Delta_A - \Delta_B & \Delta_C - \Delta_B \end{array}$$

The displacements are obtained as follows.

(ii)

$$\begin{array}{c} {}^{\mathsf{TM}_{B}} & \underline{2l_{2}} / 3^{\mathsf{E}} \overset{\dagger}{l} I_{1} & A_{1} x^{-1} \overset{\dagger}{+} \overset{\dagger}{2} M_{A} l_{1} \overset{l_{1}}{l_{1}} \overset{\dagger}{3} \overset{\dagger}{+} & 2 M_{B} l_{2} \\ & \cdot & & \cdot \\ \delta^{B} & = & \overset{\dagger}{1} & A_{2} x^{-2} & \cdot & \overset{\dagger}{1} M_{C} l_{2} & l_{2} & + & \overset{\mathsf{\Sigma}}{1} \\ & \delta^{B} & \overset{\bullet}{=} & \overset{\dagger}{+} & \overset{\mathsf{TM}_{B}}{\cdot} & \cdot & 2 l_{2} / 3 \end{array}$$

 $C E_2 I_2 2 3 2$ 

Combining the equations (i) and (ii)

 $Ml \qquad . l \qquad l \qquad \Sigma \qquad l \qquad . A x^{-} \qquad A x^{-} \Sigma$ 

 $A^{1} + 2M_{B}$  1 + 2 +  $C^{2} + 6$  1 1 + 22

 $E_1I_1 \qquad E_1I_1 \quad E_2I_2 \qquad E_2I_2 \qquad E_1I_1I_1 \quad E_2I_2I_1$ 

$$= 6 \begin{array}{c} \Delta_{A} - \Delta_{B} & \Sigma \\ \Delta_{C} - \Delta_{B} & \lambda_{C} - \Delta_{B} \\ + & l_{2} \end{array}$$
(iii)

The above equation is called as Clapeyron's equation of three moments.

In a simplified form of an uniform beam section (EI = constant); when there are no settlement of supports

$$Ax^{-} Ax^{-}\Sigma$$

$$\begin{array}{l}M_{A}l_{1} + 2M_{B}(l_{1} + l_{2}) + M_{C}l_{2} = \\ -6\end{array} \qquad (iv)$$

It is to be mentioned here that  $x_1$  and  $x_2$  are measured outwards in each span from the loads to the ends.

### 11.2.1 Procedure for Analysing the Continuous Beams using Theorem of Three Moments

(1) Draw simple beam moment diagram for each span of the beam. Compute the area of the above diagrams viz,  $A_1$ ,  $A_2$  ...  $A_n$  and locate the centroid of such diagrams  $\overline{x_1}$ ,  $\overline{x_2}$  ...  $\overline{x_n}$ . It must be re- membered that the distances  $\overline{x_1}$ ,  $\overline{x_2}$  ...  $\overline{x_n}$  are the centroidal distances measured towards the ends of each span as shown in Fig. 11j.

- (2) Identify the support moments which are to be determined viz,  $M_A$ ,  $M_B$  and  $M_C$
- (3) Apply three moment equation for each pair of spans which results in an equation or equations which are to be solved simultaneously. If the beam is of uniform section (EI = constant) and no support settlements apply equation (iv) and in case the beam is non-uniform and the support settles/raises apply equation (iii).
- (4) The solution of the equations gives the values of the support moments and the bending moment diagram can be drawn.
- (5) The reactions at the supports and the shear force diagram can be obtained by using equilibrium equations.

### 11.3 APPLICATION OF THREE MOMENT EQUATION IN CASE OF BEAMS WHEN ONE OR BOTH OF THE ENDS ARE FIXED

### 11.3.1 Propped Cantilever Beam

Consider the propped cantilever beam of span AB, which is fixed at A and supported on a prop at B. It is subjected to uniformly distributed load over the entire span. The fixed end moment at the support A can be determined by using theorem of three moments.

A' zero span

#### FIG. 11k Propped cantilever beam

As the A is fixed support, extend the beam form A to  $A^{j}$  of span 'zero length' and  $A^{j}$  is simply supported.

(1) The simple beam moment diagram is a parabola with a central ordinate of  $(wl^2/8)$ . The centroid of this bending moment diagram (symmetrical parabola) is at a distance 'l/2' from the supports A and B.

A

A

B

FIG. 111 Simple beam moment diagram

В

$$\begin{array}{cccc}
 & .2 \Sigma & .w_{l2} \Sigma \\
\text{It's area is } A & 3 & (l & & & 12 \\
 & & & & ) & = & \\
\end{array}$$

(2) The support moment diagram is drawn as

 $M_{_{A}}$ 

l

FIG. 11m Pure moment diagram

(3) Apply three moment theorem for the span AB.

. wl3 Σ. l Σ

$$M^{j}(0) + 2M_{A}(0+l) + 0 = -6$$

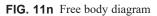
(4) The support reactions are computed by drawing the free body diagram as

÷.

$$\begin{array}{cccc}
wl^2/8 & w/m \\
A & B \\
& & & & B \\
& & & & V_B \\
\end{array}$$

12

2



$$\sum V = 0; \qquad \qquad V_A + V_B = wl$$

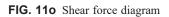
A

$$\sum M_A = 0; \quad \begin{cases} -wl^2 & wl^2 \\ 8 & 2 - V_B l = 0 \end{cases}$$

and hence

(5) Using the reactions, the shear force diagram and bending moment diagrams are obtained as





The point of contraflexure is determined by equating the bending moment expression to zero and hence

$$\frac{5wl x}{8} \quad \frac{wx^2}{2} \quad \frac{wl^2}{8} = 0$$

$$l^2 + 4x^2 - 5lx = 0$$

Solving the above equation we get x = l and

The location of maximum positive bending moment from support A is obtained by equating the shear force to zero. 5wl

$$8 - wr =$$

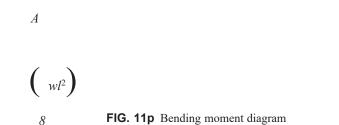
At this location, the maximum positive bending moment is obtained from 8 - wx = 0

 $-wl^2$  . 5wl  $\Sigma$ . 5l  $\Sigma$   $w(5l/8)^2$ 

Max + ve BM = 8 + 8 8 - 2

 $M_C = -8 + 64 - 128 = 128 = 0.07 wl^{2}$ 

 $0.07 \ wl^2$ 



#### 11.3.2 Beams with Both the Ends Fixed

Consider a beam AB of span l is fixed at both the ends. The beam is carrying a concentrated load of W at a distance of l/3 from the fixed end A.

As the end A is a fixed support, extend this A to A**i** of span (I**i**) of zero length and is also simply supported at A**i**. Likewise the end B is extended to B**i**.

The simply supported bending moment diagram is drawn with the maximum ordinate as  $W \times (l/3) \times (2l/3)$ 

l = 2Wl/9. The centroid of the unsymmetrical triangle is shown in Fig. 11.3j.  $\begin{array}{ccc} W & & \\ l/3 & & 2l/3 \\ l'=O & l & & l'=O \end{array}$ 

 $B^1$ 

В

## FIG. 11q Fixed beam

FIG. 11r Simple beam moment diagram

 $\binom{l+a}{3}$  —  $\binom{l+b}{3}$ 

FIG. 11s Centroid of an unsymmetrical triangle

	. 41	. 5 <i>l</i>
The centroid of the simply supported BMD is obtained using the above as	$\Sigma$ 9 from <i>A</i> and	Σ9

from *B*.

is

The support moment diagram can be drawn by identifying the support moments as  $M_A$  and  $M_B$ . Thus

 $M^{A}$ 

 $M_{B}$ 

l

FIG. 11t Pure moment diagram

Applying three moment theorem for a pair of spans of AiAB (Ref Eq (iv))  $.Wl^2 \Sigma. 5l \Sigma$ 

$$M_{A}^{i}(0) + 2M_{A}(0+l) + M_{B}(l) = 0 - \frac{6}{9} \qquad 9 \quad \times 1/l$$

 $2M_A + M_B = -0.37 Wl$ 

.*Wl*<sup>2</sup> Σ. 4*l* Σ

Considering the next pair of spans ABB<sup>j</sup>

$$M_A l + 2M_B (l + 0) + M^j (0) = -6$$

Free body diagram to determine the reactions

0.148 Wl	1/3 W	21/3	0.074 Wl
$V_{_A}$	С		V <sub>B</sub>
FIG. 11u			

Using the static equilibrium;

$$\sum_{W} V = O; \qquad V_A + V_B = W \qquad 3 \\ \sum_{W} M_A = O; \qquad -0.148 Wl + \qquad -V_B l + 0.074 Wl = O$$

0.74 W

0.26 W

FIG. 11v Shearforce diagram

0.0986 Wl

### FIG. 11w Bending moment diagram

# 11.4 NUMERICAL EXAMPLES ON CONTINUOUS BEAMS

**EXAMPLE 11.1:** A continuous beam *ABC* is simply supported at *A* and *C* and continuous over support *B* with AB = 4m and BC = 5m. A uniformly distributed load of 10 kN/m is acting over the beam. The moment of inertia is *I* throughout the span. Analyse the continuous beam and draw *SFD* and *BMD*.

A

C

FIG. 11.1a

20

31.25 kNm

FIG. 11.1b Simple beam moment diagram

C

 $-\underline{x}$ 

 $A = -x_1$ 

FIG. 11.1c Pure moment diagram

Properties of the simple beam BMD

 $A_1 = 2 \times 4 \times 20 = 53.33 \text{ kNm}^2$   $A_2 = 2 \times 5 \times 31.25 = 104.17 \text{ kNm}^2$ 

3	3	
$x_{1} = 2m$	$x_{2}^{-} =$	
$l_1 = 4 \mathrm{m}$	2.5m	
Applying three moment equation for the span ABC	<i>l</i> <sub>2</sub> = 5.0m	$Ax^{-}\Sigma$

$$Ax^{-}$$

$M_A l_1$	$+ 2M_B(l_1 + l_2) +$	=	$l_1^{1+22}l_2$
	$M_{cl_2}$	-6	<i>i</i> 1 <i>i</i> 2

$$2M_B(4+5) = -6 \begin{array}{c} .53.33 \times 2 \\ 4 \\ 5 \end{array} \begin{array}{c} 104.17 \times 2.5 \Sigma \\ 5 \\ 5 \end{array}$$

 $18M_B = -6(26.67 + 52.1)$  $M_B = -26.26 \text{ kNm}.$ 

EXAMPLE 11.2: Analyse the continuous beam by three moment theorem. Draw *SFD* and *BMD*.

10 kN

10 kN

2	4 m		3	3 m	
4	<i>D</i> 6 m	В		<i>E</i> 6 m	С

## SOLUTION

The simple beam moment diagram is drawn as

$$M_D = Wab/l = 10 \times 2 \times 4 = 13.33 \text{ kNm}$$

$$6$$

$$M_E = Wl/4 = 10 \times 6 = 15 \text{ kNm}$$

$$4$$

$$A \qquad D \qquad B \qquad E \qquad C$$
FIG. 11.2b Simple beam moment diagram
$$A \qquad B \qquad C$$
FIG. 11.2c Pure moment diagram
$$Properties of the simple beam BMD$$

$$1$$

*A* 1

$$x^{40} = 2^{-6} (6)^{13} = 3^{-3} = 3^{-7} m$$
  
 $y^{-1} = 6m$ 

$$A_2 = 2 \times 6 \times 15 = 45$$
  
 $x_2^2 = 3m$ 

$$l_2 = 6m$$

FIG. 11.4b Simple beam moment diagram

A

С

FIG. 11.4c Pure moment diagram

Properties of the simple beam BMD

 $A_1 = 2 \times 5 \times 50 = 167.5 \text{ kNm}^2$   $A_2 = 1 \times 10 \times 60 = 300 \text{ kNm}^2$ 

3  

$$x_1 = 2.5m$$
2  
 $x_2 = 10 + 6 = 5.33 m$   
 $l_2 = 10 m$ 

 $l_1 = 5.0 \text{m}$ 

. 167.5 **×** 2.5 300 **×** 5.33 Σ

 $5M_A + 2M_B(5+10) + = 5.0 10$  $10M_C -6$ 

+

 $30 M_B = -6 (83.75 + 159.9)$ 

Properties of the simple beam BMD  $\Sigma V = 0; V_A + V_{B1} = 80$  (i)  $V_{B2} + V_C = 25$  (iii)

$$\Sigma M = 0; 5V_A + 49 \frac{16(5)^2}{2} = 0$$
 (ii)

$$10V_{B2} - 25(6) - 49 = 0(iv)$$

 $V_A = 30.2 \text{ kN}$  $V_{B1} = 49.8 \text{ kN}$   $V_{B2} = 19.9 \text{ kN}$  $V_C = 5.1 \text{ kN}$ 

The simple beam moments are

$$M_D = 20 \times 10^2/8 = 250 \text{ kNm}$$
  
 $M_E = 50 \times 6 \times 2 = 75 \text{ kNm}$ 

A D B E

FIG. 11.5b Simple beam moment diagram

C

Properties of simple beam BMD

 $A_1 = 2 \times 10 \times 250 = 1666.7 \text{ kNm}^2$   $A_2 = 1 \times 8 \times 75 = 300 \text{ kNm}^2$ 

3  

$$x_1 = 5m$$
 $l_1 = 10 m$ 
 $2$ 
 $x_2 = 8 + 2 = 3.33 m$ 
 $l_2 = 8.0m$ 

Since A is fixed imagine a span AiA of zero length and Ai as simply supported. Apply three moment theorem for the spans AiAB.

 $M_{A}^{i}(0) + 2M_{A}(0 + 10) + M_{B}(10) = \begin{array}{c} .1666.7 \times 5 \quad \Sigma \\ 10 \quad + 0 \\ -6 \end{array}$ 

$$20M_A + 10M_B = -5000$$

$$2M_A + M_B = -500$$
(i)

Apply three moment theorem for the spans ABC.

$M_A(10) + 2M_B(10 + 8) + 8M_C$	= -6	. 1666 <b>.</b> 7 × 5	300 × 3.33 Σ
		10	8

$$10M_A + 36M_B = -6(833.35 + 124.875)$$
  
$$10M_A + 36M_B = -5749.35$$
 (ii)

Solving equations (i) and (ii)

Free body diagram of spans AB and BC

	B	16 kNm	4 kN/m	С
Α	D	V		V

V<sub>BI</sub>

FIG. 11.7e

FIG. 11.7d

Static equilibrium of AB

Static equilibrium of BC

$$\sum V = 0; \quad V_A + V_{B1} = 24$$
 (i)

$$\sum M = 0; \quad 4V_A + 16 - 10 - 48 = 0$$
 (ii)

$$V_{B2} + V_C = 24$$
 (iii)  
 $\sum M_B = 0;$ 

$V_A = 10.5$	$^{16} + {}^{6V}_{C} - {}^{4} \times {}^{62}_{2} = 0$
kN.	$V_C = 9.3 \text{ kN}.$
$V_{B1} = 13.5.$	$V_{B2} = 14.7$ kN.



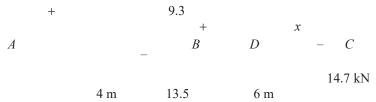


FIG. 11.7f Shear force diagram

Shear force diagram

The zero shear location in span BC is

÷

$$14.7 - 4x = 0$$
  

$$x = 3.67 \text{ m.}$$
Maximum +ve BM = 14.7(3.67) - 4(3.67)<sup>2</sup>/2 - 16 = 11 kNm  
<sup>24</sup>  
10  
- - - C  
A B 3.67 m



Free body diagram of span AB and BC

5.45 kNm	10.9 kNm		
A	В	В	С

# $M_A - 12M_A = -60$

FIG 11.8d

 $V_{_{BI}}$ 

FIG 11.8e

 $V_{_C}$ 

 $V_{_{B2}}$ 

Static equilibrium of span AB

Static equilibrium of span BC

$$\sum V = 0;$$
  

$$V_A + V_{B^1} = 0$$
 (i)  

$$\sum M_B = 0;$$

$$\sum V = 0$$
  

$$V_{B2} + V_C = 60$$
 (iii)  

$$\sum M_B = 0;$$

 $5.45 + 10.9 + 2V_A = 0$  (ii)

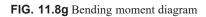
$$-10.9 + 2V_{B2} \quad \begin{array}{c} 30 \times 2^2 \\ 2 & = 0 \end{array}$$

35.5 kN/m

## FIG. 11.8f Shear force diagram

	10.9		
		9.55	
A	_		
+	В	D	С

5.45 kNm



Applying three moment theorem for the span *ABC*  $.5 \Sigma$   $.5 6 \Sigma$  6

$$M_A I + I + - 30 \times 1.5I$$
  
1.5I

## . 240 × 2.67 360 × 3 Σ

= -6 51 + 6 × 1.51

#### Snear forces and moments in members *AB* and *BC*. *Member AB*

		80 kN	
	3 m	2 m	66.67 kNm
33.76 kNm <i>V</i>		D	V
AB			BA

#### FIG. 11.9d

$$\sum V = 0;$$
  $V_{AB} + V_{BA} = 80$  (i)

$$\sum M_B = 0; \qquad 5V_{AB} + 66.67 - 33.76 - 80(2) = 0 \qquad (ii)$$
$$V_{AB} = 25.42$$
$$\therefore \quad V_{BA} = 54.58$$
$$M_D = -33.76 + 25.42(3) = 42.5 \text{ kNm}.$$

Member BC

66.67 kNm

30 kNm

FIG. 11.9e

#### FIG. 11.9i Elastic curve

**EXAMPLE 11.10:** A continuous beam *ABCD* is simply supported at *A* and continuous over spans *B* and *C*. The span *AB* is 6 m and *BC* are of length 6 m respectively. An overhang *CD* is of 1 metre length. *A* concentrated load of 20 kN is acting at 4 m from support *A*. An uniformly distributed load of 10 kN/m is acting on the span *BC*. *A* concentrated load of 10 kN is acting at *D*.

20 kN		N	10 kN/m	10 kN/m		
4 m A	E	2 m 5 m <i>B</i>	<i>F</i> 6 m	С	1 m	D

FIG. 11.10a

The simple beam moments are

$$M_E = 20 \times 4 \times 2 = 26.7 \text{ kNm}$$

62						
$M_F =$	$10 \times 8 = 45.0 \text{ kNm}$					
$M_C =$	$-10 \times 1 = -10$ kNm	L				

A E B

F

С

FIG. 11.10b Simply suppored BMD

C

#### FIG. 11.10c Pure moment diagram

Considering spans ABC

### Properties the simple beam BMD

 $A_1 = 1 \times 6 \times 26.7 = 80.1 \text{ kNm}^2$ 

 $A_2 = 2 \times 6 \times 45 = 180 \text{ kNm}^2$ 

 $\begin{array}{c} 2 & & & 3 \\ x_1 = 6 + 4 = 3.33 & & & x_2 = 3 \text{ m.} \\ m. & & & & l_2 = 6 \text{ m.} \\ l_1 = 6 \text{ m.} & & & \end{array}$ 

$$+ 2M_B \stackrel{6}{I} + 2I \stackrel{(-10)}{+} - 6M_C^{(-10)} = \begin{array}{c} . 80.1 \times 3.33 \\ 6 \\ -6 \end{array} \begin{array}{c} 180 \times 3 \Sigma \\ 6 \\ + \end{array}$$

$$18M_B - 30 = -6 (44.45 + 45)$$
$$M_B = 28.15 \text{ kNm}.$$

Shear force and bending moment values for the spans AB and BC

		20 kN	28.15 kNm
A	4	2 E	В
V <sub>AB</sub>		L	$V_{_{BA}}$

## FIG. 11.10d

Using equilibrium conditions;

$$\sum V = 0; \quad V_{AB} + V_{BA} = 20$$
 (i)

$$\sum M = 0; \quad 6V_{AB} + 28.15 - 20(2) = 0$$
 (ii)

 $\therefore \qquad M_E = V_{AB}(4) = 7.9 \text{ kNm}$ 

28.15 kNm

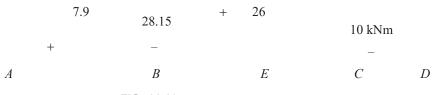
10 kN/m

10 kNm

$$\sum_{M} V = 0; V_{BC} + V_{CB} = 10(6) = 60$$
(iii)
$$\sum_{M} c = 0 \quad 10 - 28.15 + 6 V_{BC} - 10 \times 2 = 0$$
(iv)

## 18.02

# FIG. 11.10f Shear force diagram





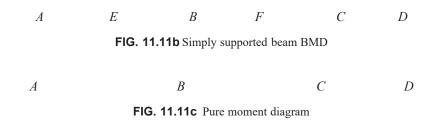
**EXAMPLE 11.11:** Analyse the continuous beam shown in figure by three moment theorem. Draw *SFD & BMD*.

20.1-11	40 kN	20 kN
30 kN	2 2	

## SOLUTION

The simple beam moments at E and F are

 $M_E = Wab = 30 \times 4 \times 2 = 40 \text{ kNm}$   $l \qquad 6$   $M_F = Wl = 40 \times 4 = 40 \text{ kNm}$   $4 \qquad 4$ 



Properties of	simply supported beam BMD
$A_1 = 1 \times 6 \times 40 = 120 \text{ kNm}^2$	$A_2 = 1 \times 4 \times 40 = 80 \text{ kNm}^2$

2 $x_1 = 6 + 4 = 2$ 3.33 $x_1 = 6.00$ 2 $x_2 = 2 m.$  $l_2 = 4.0 m. l_2 = 4.0$ 

Applying three moment theorem for spans AB & BC

 $6M_A + 2M_B(6 + 4) + 4M_C = 2 \times 6 \times 40 \times 6.00 + 4$ -6  $20M_B - 160 = -6 (66.6 + 40)$  $20M_B = -479.6$ 

Free Body diagrams

30 kN		40	) kN	
<u>4 m 2 m</u>	24 kNm	2 mF	2 m	— 40 kNm

FIG. 11.11d

 $V_{_{BI}}$ 

FIG. 11.11e

 $V_{_{B2}}$ 

24

FIG. 11.11f Shear force diagram

24 kN

40		40	40 kN	m
+	-24		_	
E	Bending	moment o	liagran	D

EXAMPLE 11.12: Draw the shear for the beam shown in figure.

## 10 kN/m

C

### FIG. 11.12a

А

A

В

С

FIG. 11.12b Simply supported beam BMD

## SOLUTION

As the end A is fixed, imagine an imaginery span  $A\mathbf{i}A$  of zero length with no load and  $A\mathbf{j}$  is simply supported.

Considering the span *A***i***AB* 

 $0 + \frac{2}{3 \times 3 \times 11.25} \sum_{1.5}^{5}$ 

j

$$M_A(0) + 2M_A(0+3) + 3M_B = -6$$

$$6M_A + 3M_B = -67.5$$

3

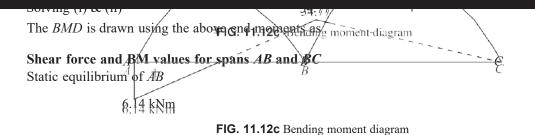
Considering the span ABC

$$.22.5 \times 1.5 \quad 180 \times 3\Sigma$$
  
 $3 \quad 6$ 

$$3M_A + 2M_B(3 + 6) + 6M_C = +$$

$$3M_A + 18M_B = -6 (11.25 + 90)$$
  

$$3M_A + 18M_B = -607.5$$
 (ii)



6.14 kNm

$$\sum B = 0; \quad 34.77 + 6.14 + 3V_{AB} - 10 \times 2 = 0$$
(ii)

CB

Static equilibrium of BC

В С

FIG. 11.12e

Maximum positive *BM* is span *AB* 34.77 kNm The location of zero shear force  $\inf AB$  zone is 29.3  $1.36 - 10\bar{x_1} = 0.$ +  $^+$  $x_1 = 0.135 \text{ m}$ В E CA + 2.42 m 35.8 6.14 FIG. 11.12f Shear force diagram FIG. 11.12g Bending moment diagram

 $M_{X1X1} = 6.19 + 1.35 (0.135) - 10 (0.135)^2/2 = 6.28$  kNm.

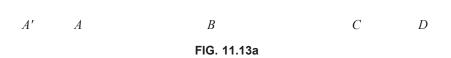
Maximum positive BM in span BC

The location of zero shear force in BC zone is

24.2 - 10 
$$x_2 = 0$$
  
 $x_2 = 2.42 \text{ m}$   
 $M_{\star 2 \star 2} = 24.2(2.42) - 10(2.42)^2/2$   
 $= 29.3 \text{ kNm}.$ 

**EXAMPLE 11.13:** A continuous beam *ABCD* is of uniform section. It is fixed at *A*, simply supported at *B* and *C* and *CD* is an overhang. AB = BC = 5 m and CD = 2 m. If a concentrated load of 30 kN acts at *D*, determine the moments and reactions at *A*, *B* and *C*. Sketch the shear force and bending moment diagram and mark in the salient values.

30 kN



## **SOLUTION**

As the end A is fixed imagine a imaginery span  $A\mathbf{i}A$  of zero length and  $A\mathbf{i}$  is simply supported. Apply three moment theorem for the spans  $A\mathbf{i}AB$ 

$$M_{A(0)} + 2M_{A}(0+5) + 5M_{B}$$
  
= -6(0+0) 10M<sub>A</sub> +  
5M<sub>B</sub> = 0  
2M<sub>A</sub> + M<sub>B</sub> = 0 (i)

## **Shear force and BM values for spans** *AB* **and** *BC Span AB*

8.57 kNm

17.14 kNm

15.43

FIG. 11.13d Shear force diagram

## 17.10 kNm

## FIG. 11.13e Bending moment diagram

**EXAMPLE 11.14:** Analyse the continuous beam by the theorem of three moments. Draw neat sketches of *SFD* and *BMD*. Clearly indicate all the salient values.

*A' A C D E* 

FIG. 11.14a

SOLUTION The simple beam moments are  $wl^2 wl = 4^2 = 4$ M

$$B = 8 + 4 = 20 \times 8 + 16 \times 4 = 56 \text{ kNm}$$
  

$$M_D = wl = 40 \times 4 = 40 \text{ kNm}$$
  

$$4 = 40 \text{ kNm}$$

A

В

С

D

Ε

FIG. 11.14b Simple beam moment diagram

A B C

FIG. 11.14c Simple beam moment diagram

Properties of simple beam BMD

 $A_1 = 2 \times 4 \times 40 + 1 \times 4 \times 16 = 138.67$   $A_2 = 1 \times 4 \times 40 = 80 \text{ kNm}^2$ 

E

3	2	2
$l_1 = 4m$		$x_2 = 2m$
$x_1 = 2m$		$l_2 = 4m$

Applying three moment theorem for span AIAC

$$\sum_{\substack{M_A \ l_1 + 2M_A}} + l_2 + M_C l_2 = -6 \frac{A_{1x_1}}{l_1} + \frac{A_{2x_2}}{l_2}$$

$$2M_A(4) + 4M_C = -6 \times 138.67 \times 2$$
  
$$8M_A + 4M_C = -416.01$$
 (i)

Applying theorem of three moments for the spans ACE

$$M_A(4) + 2M_C(4+4) + M_E(4) = \begin{array}{c} \cdot 138.67 \times 2 & 80 \times 2\Sigma \\ 4 & 4 \\ -6 & + \end{array}$$

$$4M_A + 16M_C = -6(109.335) = -656.01$$
 (ii)

Solving Equations (i) and (ii)

Free bo diagra	•						
2(1)1	2	16 kN	20 kN/m 32 kNm	32 kNm	2 m	40 kN	
36 kNm <i>V</i>	2 m	4 m	V	$V_{C2}$		4 m	Ve

B CI C D E

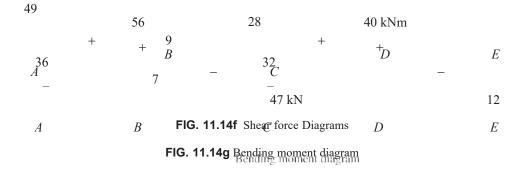
A

FIG. 11.14d

С

Static equilibrium of  
AC
 Static equilibrium of CE

 
$$\sum V = 0;$$
 $\sum V = 0;$ 
 $V_A + V_{C1} = 16 + 4(20) = 96$  (i)
  $\sum V = 0;$ 
 $\sum M_A = 0$ 
 $\sum M_E = 0;$ 
 $-36 + 32 + 4V_A - 16(2) - 20 \times 2 = 0$  (ii)
  $\sum M_E = 0;$ 
 $V_{C1} = 47 \text{ kN}$ 
 $V_{C2} + V_E = 40$  (iv)



EXAMPLE 11.15: Sketch the BMD for the continuous beam shown in figure.

60 kN

20 kN/m 30 kN

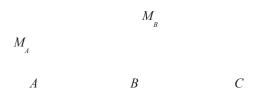
l m	3 m	

0	1			4 m	1 m
-	A	D	В	E 4 $I$	C F
			510		

FIG. 11.15a D

Ε

FIG. 11.15b Simple beam moment diagram





SOLUTION

Properties of the simple beam *BMD* 

 $A_{1} = 1 \times 4 \times 45 = 90$   $A_{2} = 2 \times 4 \times 40 = 106.7 \text{ kNm}^{2}$   $A_{2} = 2 \times 4 \times 40 = 106.7 \text{ kNm}^{2}$   $x_{2} = 2 \text{m}$   $x_{1} = 4 + 1 = 1.67 \text{ m}$   $l_{1} = 4 \text{m}$   $l_{2} = 4 \text{m}$ 

Since A is fixed assume an imaginery span of AiA of zero length with no loading. Assume Ai as simply supported. Apply three moment equation for the span AiAB,

$$M_{\mathbf{j}}(0) + 2M_A \ 0 + 4 + M_B \ 4 = -6 \ 0 + 90 \times 2.33 \times 3I$$

$$8M_A + 4M_B = -315$$
 (i)

Applying three moment theorem for the spans *AB* and *BC*;

 $.4\Sigma$  .4  $4\Sigma$   $.4\Sigma$   $.90 \times 1.67$   $106.7 \times 2\Sigma$ 

$$M_A \quad 3I \quad \stackrel{+}{2M_B} \quad 3I \quad + \quad M_C \quad 4I \quad = \\ 4I \quad -6 \quad 4 \times 3I \quad 4 \times 4I \quad .$$

$$1.33M_A + 2M_B(1.33 + 1.0) - 30 = -6 (12.525 + 13.338)$$
  
$$1.33M_A + 4.66M_B = 30 - (25.863)6$$
  
$$1.33M_A + 4.66M_B = -125.18$$
 (ii)

Solving (i) and (ii);

Free body diagrams of span AB and BC

60 kN

30.3 kNm

1 m 3 m

C

FIG 11.15d

*B1* 

FIG 11.15e

Static equilibrium of AB

Static equilibrium of BC

$$\sum V = 0;$$
  

$$V_A + V_B = 60$$
 (i)  

$$\sum M_B = 0;$$

$$\sum V = 0;$$
  

$$V_{B2} + V_C = 80$$
(iii)  

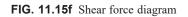
$$\sum M_B = 0$$

	42
$-30.3 + 18.1 + 4V_A -$	$-18.10 + 30 + 4V_{B2} - 20 \times 2 = 0$
$60(3) = 0 V_A = 48.05 \text{ kN}$ (ii)	$V_{B2} = 37.02 \text{ kN}.$
$V_{B2} = 11.95 \text{ kN}$	$V_C = 42.98 \text{ kN}.$



48.03	)	37.02		30	
	÷	+		+	
A	D	– <i>B</i> 1.85 <i>E</i>	_	С	F
		11.95			

42.98 kN



30.3 _	+ 45.0		18.1	4	F	15.95		30.0 kNm _	
	A	D		В	F	,	Ε		С

FIG. 11.15g Bending moment diagram

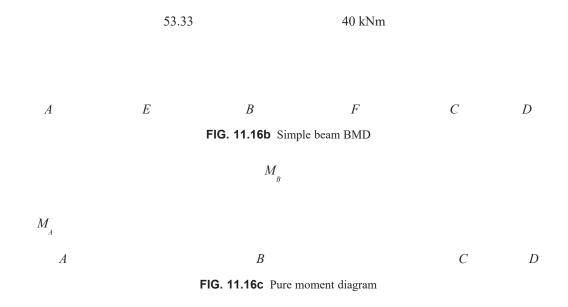
**EXAMPLE 11.16:** Analyse the continuous beam by three moment theorem. E is constant. Draw the bending moment diagram.

80 kN 1 m

...... 2 m

3 m E

A 31 B 21 C 21 FIG. 11.16a



## SOLUTION

As the end A is fixed assume an imaginery span  $A^{j}$  of zero length with no load and  $A^{j}$  is simply supported;

Apply three moment theorem for spans AJAB

$$M_{A}^{j} + 2M_{A} 0 = \frac{3}{4} \sum_{A} \frac{3}{3I} \sum_{$$

$$2M_A + M_B = -70.93$$
 (i)

Applying three moment theorem for spans ABC

. 3 Σ	. 3	4Σ	.4Σ	. 80 <b>×</b>	106.67 × 2 Σ
				1.67	

$$M_A \quad 3I \quad \frac{+}{2M_B} \quad 3I + -10 \quad = \\ 2I \quad 2I \quad -6 \quad 3 \times 3I \quad 2I \times 4$$

+

$$M_A + 6M_B - 20 = -6(14.84 + 26.67)$$
  

$$M_A + 6M_B = -249.06$$
 (ii)

borving (1) and (11)

Free Body diagrams of span AB and BC

16.05 kNm 8

80 kN

38.84 kNm

<u>2 m 1 m</u> 38.84 kNm

$V_{A}$	Ε	V <sub>BI</sub>	$V_{B2}$	4 m	$V_C$
	FIG. 11.16d		F	IG. 11.16e	

$$\sum_{V=0;} V = 0; \\ V_A + V_{B1} = 80$$
 (i) 
$$\sum_{M_B=0} V_{B2} + V_c = 80$$
 (iii) 
$$\sum_{M_C=0} M_C = 0$$

 $-16.05 + 38.84 - 80(1) + 3V_A = 0 \quad (ii)$ 

$$10 - 38.84 + 4V_{B2} \quad \begin{array}{c} 20 \times 4^2 \\ 2 &= 0 \end{array} \quad (iv)$$

 $M_E = -17.86 + 20.88(2)$ = 23.9 kNm

The location of zero shear in zone BC is obtained from

$$47.21 - 20x = 0$$
  
 $x = 2.36$  m

	<b>= -</b> 38.84	47.21	2.36		$2.36^{2}$
∴ Max +ve	+	×	-	20	2
BM				×	

= 16.88 kNm

At the midspan of BC;

$$M = -38.84 + 47.21 \times 2 - 20 \times 2 = 15.58 \text{ kNm}$$

	19.07			47.21				
	+			47.21		20		
				+		+		
	Α	E		В		С	D	
				_	-	-		
		60.9	93		3	33.79		
				<b>FIG. 11.16</b> f S	hear force diagram			
		53	3.33		15.58			
16.05		+		38.84	+		10 kNm	
-				_			_	
A	2 1	n E	1 m	В		2.32 m	<i>C</i> 1 m	D
FIG. 11.16g Bending moment diagram								

**EXAMPLE 11.17:** A continuous beam ABC is fixed at A and C. It is continuous over a simple support B. Span AB is 5 m while BC span is 6 m. It is subjected to a concentrated load of 60 kN at 3 m from A and the span BC is subjected to uniformly distributed load of 10 kN/m. The ratio of flexural rigidity of span BC to BA is 1.5. Sketch the shear force and bending moment diagram. Use Clapeyron's theorem of three moments.

60 kN

10 kN/m

3 m 2 m

6 m

С

FIG. 11.17a

A

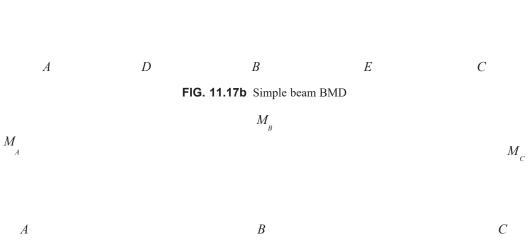
## SOLUTION

The simple beam moments are

$$M_D = Wab = 60 \times 3 \times 2 = 72 \text{ kNm}$$

$$M_E = \begin{cases} l & 5\\ wl^2 & 10 \times \\ 8 = & 6^2\\ 8 & = 45 \text{ kNm} \end{cases}$$

FIG. 11.16f Shear force diagram



45 kNm

72

## FIG. 11.17c Pure moment diagram

Since *A* is fixed imagine a span of zero length  $A\mathbf{i}A$  with no load and  $A\mathbf{j}$  is simply supported. Apply three moment theorem for the spans  $A\mathbf{i}AB$ 

Properties of the simple beam BMD

$A_1 = 0$	$A_2 = \frac{1}{2} \times 5 \times 72 = 180$
$x_1 = 0$	$x_2 = 5 + 2 = 2.33$
$l_1 = 0$	$l_2 = 5.0$

$$M_{j} \cdot \frac{\Sigma + 2M_{A} \cdot l^{-1} + L_{2} \Sigma}{l_{1}} + \frac{\Sigma}{l_{2}} + \frac{\Sigma}{M_{B}} \cdot \frac{\Sigma}{l_{2}} = \frac{A_{A} \cdot x}{-6} + \frac{\Delta x}{l_{1}} + \frac{A_{2} \cdot x_{2}}{A_{2} \cdot x_{2}}$$

$$\begin{array}{cccc} .5\Sigma & .5\Sigma \\ 2M_A & I & + & I \\ M_B & -6 \end{array} \quad \begin{array}{c} .180 \times 2.33\Sigma \\ 5 \times I \end{array}$$

Apply three moment theorem for the spans ABC

Properties of the simple beam BMD

$A_1 = 180 \text{ kNm}^2$	$A_2 = 2 \times 6 \times 45 = 180 \text{ kNm}^2$
$x_1 = 5 + 3 = 2.67 \text{ m}$ $l_1 = 5 \text{m}$	$x_2 = 3m$ $l_2 = 6m$

. 5 Σ . 5 6 Σ . 6 Σ . 180 × 2.67 180 × 3 Σ

$$5M_A + 18M_B + 4M_C = -6 (96.12 + 60)$$
  

$$5M_A + 18M_B + 4M_C = -936.72$$
 (ii)

Applying three moment theorem BCCi

As the end *C* is fixed imagine a span *CC*<sup>I</sup> of zero length and *C*<sup>I</sup> is simply supported

	31.62 kNm		60 kN		37.4 kNm
A	V	3 m	D	2 m	B V

AB

## FIG. 11.17d

$$\sum V = 0; V_{AB} + V_{BA} = 60$$
 (i)

$$\sum M_B = 0; \quad 5V_{AB} - 60(2) - 31.62 + 37.4 = 0$$
(ii)  
$$V_{AB} = 22.84 \text{ kN}$$
$$V_{BA} = 37.16 \text{ kN}$$

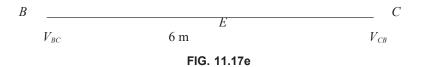
Span BC

$$M_D = 22.84(3) - 31.62 = 36.9 \text{ kNm}$$

37.4 kNm

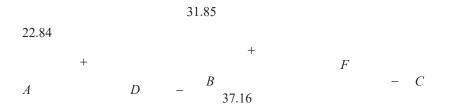
10 kN/m

26.29 kNm



$$\sum_{M} V = 0; \quad V_{BC} + V_{CB} = 60$$
(iii)  
$$M \sum_{M} c = 0; \quad -37.4 + 26 \frac{29}{32} + 6 V_{BC} - 10 \times 2 = 0$$

$$E = 31.85(3) - 37.4 - 10 \times 2 = 13.15$$
 kNm



28.15 kN 2.81

5

FIG. 11.17f Shear force diagram

The location of zero shear in span CB is obtained by equating the shear force equation to zero as

$$(SF)_{xx} = 28.15 - 10x = 0$$
  
 $x = 2.815 \text{ m}$   
 $M_F = 28.15(2.815) - 10(2.815)^2/2 - 26.29$   
 $= 13.2 \text{ kNm}$ 

31.62	+ 37.49	37.4	+ 13.15	26.29 kNm
A	D	В	F	С

FIG. 11.17g Bending moment diagram

**EXAMPLE 11.18:** A continuous beam *ABCD* is of uniform section as shown in figure. *EI* is constant. Draw the *SFD* and *BMD* 

10 kN/m

A 6 m B 6 m C 6 m D

*E F G* 

FIG. 11.18a

## SOLUTION

The simple beam moments are

$$M_E = M_F = M_G \qquad \begin{array}{c} 10 \times 6^2 \\ 8 \end{array} = 45 \text{ kNm}$$

	45	45		45 kNm	
A		В	С		D
FIG. 11.18b Simple beam BMD					
		MB	M <sub>c</sub>		
A		В	С		D

Considering spans ABC

$$A_1 = 2 \times 6 \times 45 = 180 \text{ KNm}^2$$
  
 $x_1 = 3 \text{m}$ 

$$+ 2M_B(6+6) + 6M_C = \begin{array}{c} . \ 180 \times 3 \\ 6 \\ -6 \end{array} \begin{array}{c} . \ 180 \times 3 \\ 5 \\ -6 \end{array}$$

$$24M_B + 6M_C = -6(90 + 90) = -1080 \tag{1}$$

Considering span BCD

$$6M_B + 2M_C(6+6) + 6M_D = \begin{array}{c} .180 \times 3 & 180 \times 3 \Sigma \\ 6 & 6 \\ -6 & + \end{array}$$

10 kN/m 36 kNm A\_\_\_\_\_\_ B

$$\sum B = 0; \ 6V_{AB} + 36 - 10 \times 2 = 0$$
(ii)

÷

Consider span BC

2(1)	10 kN/m	
36 kNm		36 kNm
B <sub>V</sub>	6 m	<sub>V</sub> C

$$\sum_{M} V = 0; \quad V_{BC} + V_{CB} = 60$$
(iii)  
M 62

CB

$$\sum c = 0; \quad \begin{cases} V_{BC} = 36 \pm 36 \pm 10 \text{ m}^2 \text$$

Span CD

36 kNm

10 kN/m

$$\sum D = 0; \ 6V_{CD} - 36 - 10 \times 2 = 0 \qquad 2.4$$

FIG. 11.18g Shear force diagram

The location of zero shear is calculated as

$$24 - 10x_1 = 0$$
  

$$x_1 = 2.4m$$
  

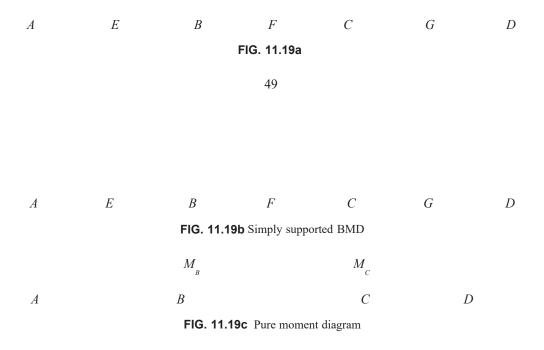
$$M_E = 24(2.4) - 10(2.4)^2/2 = 28.8 \text{ kNm}$$
  

$$M_F = 30(3) - 36 - 10 \times 3^2/2 = 9.0 \text{ kNm}$$
  

$$M_G = 24 (2.4) - 10(2.4)^2/2 = 28.8 \text{ kNm}$$

A	E	В	F	С	G	D
		_		_	+	
	+ 28.8	36	+ 9	36	28.8 kNm	

FIG. 11.18h Bending moment diagram



SOLUTION

Properties of the simple beam *BMD* 

$A_1 = 2 \times 3 \times 28.1 = 56.2$	$A_2 = 2 \times 2.8 \times 49 = 91.47$	$A_3 = 80 \text{ kNm}^2$
$A_1 = 2 \times 3 \times 20.1 = 50.2$ kNm <sup>2</sup>	kNm <sup>2</sup>	$x_3 = 2m$
$x_1 = 1.5 \text{m}$	$x_2 = 1.4$ m	$l_3 = 4m$
$l_1 = 3m$	$l_2 = 2.8 { m m}$	

Applying three moment theorem for spans ABC	. 56.2 × 1.5	
	3	91.47 × 1.4 Σ
$M_A(3) + 2M_B(3 + 2.8) + 2.8M_C =$		2.8
-6	+	

$$11.6M_B + 2.8M_C = -6(28.1 + 45.74)$$
  
$$11.6M_B + 2.8M_C = -443$$
 (i)

Applying three moment theorem for spans BCD

$$2.8M_B + 2M_C(2.8 + 4) + 4M_D = -6$$

$$.91.47 \times 1.4 \quad 80 \times 2\Sigma$$

$$2.8 \quad 4$$

$$2.8M_B + 13.6M_C = -6 (45.74 + 40)$$
  
$$2.8M_B + 13.6M_C = -514.44$$
(ii)

Solving (i) and (ii)

Free body diagrams of AB, BC and CD

25 kN/m 30.58 kNm

30.58 kNm 50 kN/m 31.53 kNm 31.53 kNm 15 kN/m

 $V_{A} = 3 \text{ m} \qquad V_{B1} \qquad \qquad V_{B2} = 2.8 \text{ m} \qquad V_{C1} \qquad V_{C1} = 4.0 \text{ m} \quad V_{D}$ 

FIG. 11.19d

Static equilibrium of spans AB, BC and CD

$$\Sigma V = 0; \qquad \Sigma V = 0; \qquad V_A + V_{B1} = 75 \qquad (i) \qquad V_{B2} + V_{C1} = 140 \quad (iii) \qquad V_{C2} + V_D = 60 \quad (v) \qquad \Sigma M_D = 0; \qquad \Sigma M_D = 0; \qquad \Sigma M_D = 0; \qquad \Sigma M_D = 0;$$

$3V_A + 30.58 \frac{25}{2}$	$_{0} = 0$	(ii) 31	.53 - 30.58 +	42	
$3V_A + 30.58$ 2:	$\times 3^2$		$2.8V_{B2}$	$-31.53 + 4V_{C^2} - 15 \times 2 = 0$	(vi)
			$2.8^{2}$		

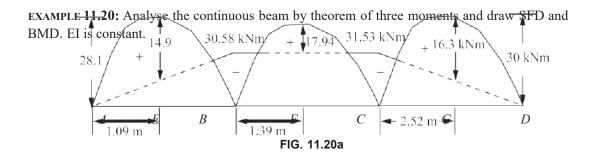
 $-50 \times 2 = 0$  (iv)

$V_A = 27.3 \text{ kN}$	$V_{B2} = 69$ kN	.66	$V_{C^2} = 151.53/4 = 37.88$ kN
$V_{B1} = 47.7$		24	
kN	$V_C = 70.$ kN	.34	$V_D = 22.12 \text{ kN}$
27.3	69.66 <sup>KIN</sup>	37.88	
+	+	+	
x	x	x	
1	— 2	- 3	_
	47.7 kN	70.34	22.12
		lear force diagram	

The locations of shear forces in zones AB, BC and CD are

$$27.3 - 25x_{1} = 0$$

$$14.9 + 1.09^{30} = 1.09^{30} = 1.39^{31} = 1.09^{2} = 1.39^{31} = 1.39^{31} = 1.09^{30} = 1.39^{31} = 1.39^{31} = 1.09^{30} = 1.39^{31} = 1$$



A

В

FIG. 11.20b Simple beam BMD for span ABC

C

C

FIG. 11.20c Simple beam BMD for span BCD

FIG. 11.20d Pure moment diagram

**SOLUTION** Referring to Fig. 11.20 b

Properties of simple beam BMD

$$A_{1} = 1 \times 10 \times 4 = 20 \text{ kNm}^{2}$$

$$A_{2} = 2 \times 6 \times 22.5 = 90 \text{ kNm}^{2}$$

$$x_{1} = 2m$$

$$l_{1} = 4m$$

$$l_{2} = 6m$$

Applying three moment theorem for spans ABC,

$4M_A + 2M_B(4 + 6) + 6M_C =$	. 20 × 2	90 <b>×</b> 3 Σ
-6	4	6
	+	

$$20M_B + 6M_C = -6(10 + 45)$$
  
$$20M_B + 6M_C = -330$$
 (i)

Referring to Fig. 11.20 c

Properties of simple beam BMD

$$A_{1} = 2 \times 6 \times 22.5 = 90$$

$$A_{2} = 1 \times 5 \times 18 = 45 \text{ kNm}^{2}$$

$$A_{2} = 5 \times 18 = 45 \text{ kNm}^{2}$$

$$A_{2} = 5 \times 18 = 45 \text{ kNm}^{2}$$

$$A_{2} = 5 \times 18 = 45 \text{ kNm}^{2}$$

$$A_{2} = 5 \times 18 = 45 \text{ kNm}^{2}$$

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$$A_{2} = 5 \times 18 = 45 \text{ kNm}^{2}$$

$$A_{3} = 5 \times 18 = 45 \text{ kNm}^{2}$$

$$A_{2} = 5 \times 18 = 45 \text{ kNm}^{2}$$

$$A_{3} = 5 \times 18 = 45 \text{ kNm}^{2}$$

$$A_{4} = 1 \times 5 \times 18 = 45 \text{ kNm}^{2}$$

$$A_{2} = 5 \times 18 = 45 \text{ kNm}^{2}$$

$$A_{3} = 5 \times 18 = 45 \text{ kNm}^{2}$$

$$A_{4} = 1 \times 5 \times 18 = 45 \text{ kNm}^{2}$$

$$A_{4} = 1 \times 5 \times 18 = 45 \text{ kNm}^{2}$$

$$A_{4} = 1 \times 5 \times 18 = 45 \text{ kNm}^{2}$$

$$A_{4} = 1 \times 5 \times 18 = 45 \text{ kNm}^{2}$$

$$A_{4} = 1 \times 5 \times 18 = 45 \text{ kNm}^{2}$$

$$A_{4} = 1 \times 5 \times 18 = 45 \text{ kNm}^{2}$$

$$A_{4} = 1 \times 5 \times 18 = 45 \text{ kNm}^{2}$$

$$A_{4} = 1 \times 5 \times 18 = 45 \text{ kNm}^{2}$$

$$A_{4} = 5 \times 10^{10} \text{ km}^{2}$$

$$A_{4} = 5 \times 10^{10} \text{ km}^{2}$$

$$A_{4} = 5 \times 10^{10} \text{ km}^{2}$$

$$A_{5} = 5 \times 10^{10} \text{ km}^{2}$$

$$A_{6} = 5 \times 10^{10} \text{ km}^{2}$$

$$A_{6} = 5 \times 10^{10} \text{ km}^{2}$$

$$A_{7} = 5 \times 10^{10} \text{ km}^{2}$$

$$A_{7} = 5 \times 10^{10} \text{ km}^{2}$$

$$A_{8} = 45 \text{ km}^{2}$$

$$A_{8} = 45 \text{ km}^{2}$$

$$A_{8} = 5 \times 10^{10} \text{ km}^{2}$$

$$A_{8} = 5 \times 10^{10} \text{ km}^{2}$$

$$A_{8} = 45 \text{ km}^{2}$$

Applying three moment theorem for spans BCD Considering span BCD

$$6M_B + 2M_C(6+5) + 5M_D = \begin{array}{c} .90 \times 3 \\ 6 \\ -6 \end{array} \begin{array}{c} 45 \times 2.33 \Sigma \\ 5 \\ + \end{array}$$

$$6M_B + 22M_C = -6(45 + 20.97)$$
  

$$6M_B + 22M_C = -395.82$$
(ii)

Solving (i) and (ii)

$$M_B = 12.09$$
 kNm.  
 $M_C = 14.69$  kNm.

Shear force and bending moment values for spans AB, BC and CD.



.09 kNm

#### FIG. 11.20e

$$\sum V = 0; \quad V_{AB} + V_{BA} = 10$$
 (i)

$$\sum M_B = 0; \quad 4V_{AB} + 12.09 - 10(2) = 0$$
 (ii)

Solving (i) and (ii)

 $M_E = 1.98(2) = 3.96$  kNm

Span BC

12.09 kNm

5 kN/m

14.69 kNm

# FIG. 11.20f

$$\sum V = 0; V_{BC} + V_{CB} = 6(5) = 30 \text{ kN}$$
 (iii)

$$\sum M_B = 0; \quad 6V_{BC} + 14.69 - 12.09 \quad \begin{array}{c} 5 \times 6^2 \\ 2 &= 0 \end{array}$$

The location of shear force is zero is found out as

$$14.56 - 5x = 0$$
  
 $x = 2.91 \text{ m}$ 

Marce BM 14 56 2 91 12 09 5 <sup>2.91<sup>2</sup></sup> 9 11 kNm

$$+$$
 = . (.) .  $- \times$  2 = .

Span CD

14.69 kNm

#### $\angle MD = 0; \quad SVCD = 14.09 = 13(2) = 0$

1.98		14.56	8.94	
	+	+	+	
A	E	В	С	D
		- 8.02	- 14.69	– 6.06 kN

FIG. 11.20h	Shear force	diagram
-------------	-------------	---------

	3.96 +	12.09	+ 9.11	15.44 kNm _	+ 12.12	
A	Ε	В		С		D
		FIG. 11.20i	Bending moment diagra	am		

**EXAMPLE 11.21:** A continuous beam *ABCD* is simply supported at *A* and *D*. It is continuous over supports *B* and *C*. AB = BC = CD = 4 m. EI is constant. It is subjected to uniformly distributed load of 8 kN/m over the span *BC*. Draw the shear force diagram and bending moment diagram.

#### 8 kN/m

A	В	Ε	С	D

## SOLUTION

The simple beam moment

$$M_F = \begin{cases} 8 \times 4^2 \\ 8 = 16 \text{ kNm} \end{cases}$$

# 16 kNm

A	В	E	С	D	
	FIG. 11.21b Sim	ple beam bendin	g moment diagram		
	$M^{\scriptscriptstyle B}$		$M_{_C}$		
A	В		С	D	
	FIG. 11.	<b>21c</b> Pure momer	nt diagram		
Consider span ABC Applying three moment theorem;					

$$4M_{A} + 2M_{B}(4 + 4) + 4M_{C} = \begin{matrix} 0 + 2 & 4 \times 16 \times 2 \Sigma \\ 0 + 2 & 4 \end{matrix}$$

$$16M_B + 4M_C = -128$$
 (i)

(ii)

Consider span BCD

$$.2 \quad 4 \times 16 \times 2 \quad \Sigma$$
  

$$4M_B + 2M_C(4 + 4) + 4M_D = -6 \qquad 3 \times 4 + 0$$
  

$$4M_B + 16M_C = -128$$

6.4 kNm

8 kN/m

6.4 kNm



## FIG. 11.21e

$$\sum V = 0; V_{BC} + V_{CB} = 8(4) = 32$$
(iii)

$$\sum M_C = 0; \quad -6.4 + 6.4 + 4V_{BC} \quad 2 = 0$$
 (iv)

span CD

6.4 kNm C

D

$$B = \sum M_D = 0; \quad -6.4 + 4V_{CD} = C0 \qquad D \qquad (vi)$$

-1.6

A

**EXAMPLE 11.22:** Analyse the beam shown in figure by SFD and BMD. EI is constant.  $_{16}^{16}$ 

# FIG. 11.21g Shear Revenagram

#### 16 kNm

A	В	С	D
	_	_	
	+ 6.4	6.4	

FIG. 11.21h Bending moment diagram

A	6 m	В	6 m	C	6 m	D	6m	Ε
			FIG.	11.22a				

*A B C D E* 

FIG. 11.22b Simple beam BMD

 $\begin{array}{ccc} M_{_B} & M_{_C} & M_{_D} \\ \end{array}$ 

## FIG. 11.22c Pure moment diagram

Properties of simple beam *BMD* 

$A_1 = 2 \times 6 \times 45 = 180$	$A_2 = 2 \times 6 \times 45 = 180 \text{ KNm}^2$
3	3
$x_1 = 3m$	$x_2 = 3m$
$l_1 = 6m$	$l_2 = 6m$

Applying 3 moment theorem for the spans ABC

6

.

 $6M_A + 2M_B(6 + 6) + 6M_C = -60$  +

$$24M_B + 6M_C = -540$$
 (i)

Applying 3 moment theorem for the spans BCD

$$6M_B + 2M_C(6+6) + 6M_D = \begin{array}{c} \cdot 180 \times 3 \\ 6 \\ -6 \\ + \end{array} \begin{array}{c} 180 \times 3 \Sigma \\ 6 \\ 6 \\ + \end{array}$$

$$6M_B + 24M_C + 6M_D = -6(180) = -1080$$
  

$$M_B + 4M_C + M_D = -180$$
(ii)

Applying 3 moment theorem for spans CDE

$$6M_C + 2M_D(6+6) + 6M_E = 6 + 0$$





$$\sum V = 0; \quad V_{AB} + V_{BA} = 0 \tag{1}$$
$$\sum M_B = 0; \quad 6V_{AB} + 12.86 = 0 \tag{1}$$

span BC

12.86 kNm

10 kN/m

В		C
$V_{BC}$	6 m	$V_{CB}$

## FIG. 11.22e

$$\sum V = 0; V_{BC} + V_{CB} = 60$$
 (iii)

$$\sum M_C = 0; \quad -12.86 + 38.57 + 6V_{BC} \quad 2 = 0$$
 (iv)

span CD

38.57 kNm	10 kN/m	12.86 kNm
C V <sub>CD</sub>	6 m	D V <sub>DC</sub>

12.86 kNm

 $V_{\rm DE}$ 

6 m

 $V_{\rm ED}$ 

FIG. 11.22g

SOLUTION

$$M_B = -20(1) = -20 \text{ kNm}$$

The simple beam moments are

 $M_F = \begin{array}{c} 20 \times 4^2 \\ 8 \end{array} = 40 \text{ kNm}$ 

			<b>×</b> 4 = 60 kNm 4		
		40 kNm		60 kNm	
В	С	F	D	G	Ε
		FIG. 11.23b (	b) Simple beam BMD		
			M		
20					
В		С	D		E
		FIG. 11.23c (c)	) Pure moment diagram		
Apply 3 moment th	eorem for the s	pans BCD	. 2	2 Σ	

 $-20(3) + 2M_C(3+4) + M_D(4) = 0 + 3 \times 4 \times 40 \times 4$ -6

$$-60 + 14M_C + 4M_D = -320$$

$$14M_C + 4M_D = -260$$
(i)

Apply 3 moment theorem for the spans CDE

 $M_{C}(4) + 2M_{D}(4+4) + 4M_{E} = 3 \times 4 \times 40 \times 4 + 2 \times 4 \times 60 \times 4$ -6

$$4M_C + 16M_D = -6(53.33 + 60) = -680$$

Solving (i) and (ii)

(ii)

+ 
$$6EI \frac{\delta_A}{L_1} + \underbrace{\delta_2}_{\Sigma_2}^C \Sigma$$
  
 $A_1x_1 = 960$   
 $A_2x_2 = \underbrace{2}_3 \times 6 \times 180 \times 3 = 2160$ 

 $\Sigma \ 960 \quad 2160 \ \Sigma \qquad . \ 240 \qquad 120 \ \Sigma$ 

Substituting,  $M_A \times 4 + 2M_B(4+6) = 4 + 6 + EI \times 4 + EI \times 6$ 

$$4M_A + 20M_B = -3120 \longrightarrow M_A + 5M_B = -780$$
(2)

Solving (1) and (2),	$M_A = -163.33$	hogging BM.
kNm		
	$M_B = -123.33$	
	kNm	

240 kN

KI V

40 kN/m

163.33 kNm 2 m

2 m

A	В	В	6 m	O C
130 kN	110 kN	140.56 kN		94.44 kN

**FIG. 11.25d** Free body diagram of spans *AB* and *BC* 

130 kN

140.56

A

В

C 94.44

FIG. 11.25e Shear force diagram

110

	240		
163.33 kNm	+	123.33	+ 180
		_	

FIG. 11.25f Bending moment diagram

Ans:

## $R_A = 45$ kN, $R_B = 165.5$ kN, $R_C = 69.5$ kN

(11.3) A continuous beam of uniform section ABCD is supported and loaded as shown in Figure. (11.3) A continuous beam of uniform section ABCD is supported and loaded as shown in Figure. If If the support B sinks by 10 mm, determine the resultants and moments at the supports. the support B sinks by 10 mm, determine the resultants and questions at the supports. Assume  $E = 2(10)^5 \text{ N/mm}^2$ ;  $I = 6(10)^7 \text{ mm}^4$ 

C

10 kN/m

40 kN



A 4 m B 6 m  $C \ln D$ 

*EI* = *Constant* 

$$V_{AB} = +16.5 \text{ kN}, V_{BA} = +23.5, V_{BC} = +19, V_{CB} = +21.0$$
  
 $M_B = -14 \text{ kNm}$ 

(11.4) Determine the reactions at A, B and C of the continuous beam shown in figure.

8 kN

3 kN/m



$$V_{AB} = 6.75 \text{ kN}, V_{BA} = 1.25, V_{BC} = 6.31; V_{CB} = 8.69$$
  
 $M_A = -3.31 \text{ kNm}, M_B = -3.87, M_{CB} = +7.44$ 

(11.5) Analyse the continuous beam shown in Figure and determine the reactions

80	kN	50 kN/m	40 kN		
1 m	2 m	50 KIV/III	2 m	2 m	
4 m		4 m	4 m		

В

C

Ans:

$$V_{AB} = 41.68$$
 kN,  $V_{BA} = 38.32$ ,  $V_{BC} = 102.88$ ,  $V_{CB} = 97.12$   
 $V_{CD} = 28.03$ ,  $V_{DC} = 11.97$ ,  $M_A = -17.98$  kNm,  
 $M_B = -52.93$ ,  $M_C = -41.42$ ,  $M_D = -9.29$  kNm

(11.6) Analyse three span continuous beam by three moment theorems. Draw the BMD and shear force diagram. Determine the end moments and reactions *EI* is constant.

(11.7) Analyse and draw BMD and SFD for the beam shown in Figure. The values of second moment area of each span are indicated along the members. Modulus of elasticity is constant.

100 kN

30 kN/m

	2.5 m	2.5 m			31		1.25 m	2.5 m	1.25 m
			_				4I		
	Ī		В	6 m			С		D
A							0		

$$M_A = -56.02 \text{ kNm}, \quad M_B = -75.47 \text{ kNm}, \quad M_C = -94.3 \text{ kNm}, \quad M_D = 0$$

(11.11) Determine the reactions and the support moment at *B*. Using Clapeyron's three moment theorem.

- $V_A = 4.81$  kN,  $V_B = 0.31$ ,  $V_C = 4.88$  kN,  $M_B = -0.72$  kNm
- (11.12) Analyse the continuous beam by three moment theorem, determine the support moments. No loads on span *AB*.

0.5 kN

2.5 kN

$$M_A = -1.09$$
 kNm,  $M_B = -2.188$  kNm,  $M_C = -7.5$  kNm

#### UNIT - VI

#### **CONTINUOUS BEAMS - SLOPE DEFLECTION METHOD**

#### 3.1 Introduction:-

The methods of three moment equation, and consistent deformation method are represent the FORCE METHOD of The slope deflection analysis, structural method use unknowns, hence this method displacements is the as displacement method.

In this method, if the slopes at the ends and the relative displacement of the ends are known, the end moment can be found in terms of slopes, deflection, stiffness and length of the members.

In- the slope-deflection method the rotations of the joints are treated as unknowns. For any one member bounded by two joints the end moments can be expressed in terms of rotations. In this method all joints are considered rigid; i.e the angle between members at the joints are considered not-to change in value as loads are applied, as shown in fig 1.

joint conditions:- to get  $\theta_B \& \theta_C M_{BA} + M_{BC} + M_{BD} =$ 

0 ..... (1)

▼\_\_\_\_\_

# Figure (1)

### 3.2 ASSUMPTIONS IN THE SLOPE DEFLECTION METHOD

This method is based on the following simplified assumptions.

- All the joints of the frame are rigid, i.e, the angle between the members at the joints do not change, when the members of frame are loaded.
- 2- Distortion, due to axial and shear stresses, being very small, are neglected.

### 3.2.1 Degree of freedom:-

The number of joints rotation and independent joint translation in a structure is called the degrees of freedom. Two types for degrees of freedom.

# In rotation:-

For beam or frame is equal to D<sub>r</sub>.

$$\mathbf{D}_{\mathbf{r}} = \mathbf{j} - \mathbf{f}$$

Where:

 $D_r$  = degree of freedom.

j = no. of joints including supports.

F = no. of fixed support.

In translation:-

For frame is equal to the number of independent joint translation which can be give in a frame. Each joint has two joint translation, the total number or possible joint translation = 2j. Since on other hand each fixed or hinged support prevents two of these translations, and each roller or connecting member prevent one these translations, the total number of the available translational restraints is;

2f + 2h + r + m where f = no. of fixed supports. h = no. of hinged supports. r = no. of roller supports.m = no. of supports.

The degree of freedom in translation, Dt, is given by:-

 $\mathbf{D}_{t} = 2\mathbf{j} \cdot (2\mathbf{f} + 2\mathbf{h} + \mathbf{r} + \mathbf{m})$ 

The combined degree of freedom for frame is:-

 $D = D_r + D_t$ = j-f + 2j - (2f + 2h + r + m)

$$\mathbf{D} = 3\mathbf{j} - 3\mathbf{j} - 2\mathbf{h} - \mathbf{r} - \mathbf{m}$$

The slop defection method is applicable for beams and frames. It is useful for the analysis of highly statically indeterminate structures which have a low degree of kinematical indeterminacy. For example the frame shown in fig. 2.a

The frame (a) is nine times statically indeterminate. On other hand only tow unknown rotations,  $\theta_b$  and  $\theta_c$  i.e Kinematically

indeterminate to second degree- if the slope deflection is used. The frame (b) is once indeterminate.

# 3.3 Sign Conventions:-

Joint rotation & Fixed and moments are considered positive when occurring in a clockwise direction.

$$\begin{array}{c} = 2 \\ \theta \text{ Al} \end{array} \begin{array}{c} = 2 \\ \text{MA.L} \\ 3 \text{ 2 EI} \end{array} = \text{MA.L}$$

$$\theta = \underline{1} = \underline{MA.L} = -MA.L$$

### BI 3 2 EI 6 EI

hence  $\theta B1 = \frac{1}{2 \theta A1}$ 

# $\theta A2 = \underline{1}$ <u>MB.L</u> = <u>-MB.L</u>

3 2 EI 6 EI

 $\theta = 2 \text{ MB.L} = \text{MB.L}$ 

# B2 3 2 EI 3 EI

-

-

$$\theta_{B1} + \theta_{B2} = 0$$

Hence:  $M_A = 2M_B$ 

and  $\theta_A = \theta_{A1} - \theta_{A2}$ 

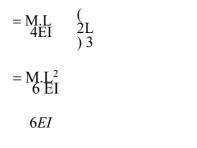
$$= \begin{array}{cc} M_{A.L} & M_{A.L} \\ 3 EL & 12 EL \end{array}$$

$$\theta_A = \frac{3MA.L}{12EI}$$

$$MA = 4EI.\theta A$$
$$L$$
$$MB = 2EI.\theta A$$
$$L$$

 $\underline{Relation \ between \ \Delta \ \& \ M}$ 

 $R = \Delta$ L
by moment area method or
by conjugate beammethod.  $\Delta = \sum_{M \text{ at } B}$ 



- -

$$\begin{array}{cc} M = & \Delta \\ & L_2 \end{array}$$

=  $\mathop{\mathrm{EI}}_{\mathrm{L}}$ .R R (+ ve) when the rotation of member AB with clockwise.

### 3.4 Fixed and moments:

As given in the chapter of Moment distribution method.

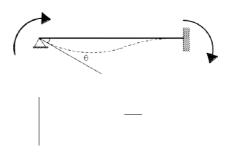
# 3.5 Derivation of slope deflection equation:-

Ma1  $= \frac{4EI\theta}{L}_{A}$ 

 $\mathbf{M}_{\mathbf{b}1} = \frac{2EI\theta}{L}_{A}$ 

 $M^{a2} = \frac{2EI\theta}{L}B^{B}$ 

Mb2  $= \frac{4EI\theta}{L}_{B}$ 



Required M<sub>ab</sub> & M<sub>ba</sub> in term of

(1) θ<sub>A</sub>, θ<sub>B</sub> at joint
 (2) rotation of member (R)
 (3) loads acting on member

#### First assume:-

Get  $Mf_{ab}$  &  $Mf_{ba}$  due to acting loads. These fixed and moment must be corrected to allow for the end rotations  $\theta_A, \theta_B$  and the member rotation R.

The effect of these rotations will be found separately.

$$\begin{array}{ccc} & = 4 E I & .\theta \\ M_a & L & _A \\ 1 & 2 E I \end{array}$$

 $M_{b1} = \begin{array}{c} .\theta \\ L \\ A \end{array}$   $M_{b2} = 4EI \\ L \\ .\theta B$ 

$$M_{a} = \frac{2EI}{L} \cdot \theta B$$

$$M_{b3} = M_{a3} \qquad \begin{array}{c} = -6 \text{ EI} \\ .\Delta \text{ L}_2 \end{array}$$

$$=$$
 - 6 EI .R  
L

by Superposition;

$$M_{ab} = Mf_{ab} + M_{a1} + M_{a2} + M_{a3}$$

In case of relative displacement between the ends of members, equal to zero (R = 0)

$$M_{ab} = Mf \qquad \begin{array}{c} + & 2EI \\ L \\ & (2\theta_a + \theta_b) \end{array}$$

$$M_{ba} = Mf_{ba} + EI (2\theta_b + \theta_A) \\ L$$

2 EI

The term (L) represents the relative stiffness of member say (K) <u>hence:</u>

$$= Mf + K_{ab} (2\theta_A + \theta_b)$$
  
M<sub>ab</sub> <sub>ab</sub>

 $M_{ba} = Mf_{ba} + K_{ba}(2\theta_B + \theta_a)$ 

Note:

 $\Delta = R$  is (+ ve) If the rotation of member with clockwise.

And (- ve) If anti clockwise.

$$M = - \mathop{6}_{L_2} \text{EI } \Delta \quad (\text{with } + \text{ve } R)$$

$$M = -6 \underset{L_2}{\text{EI}} .\Delta \quad (\text{with } -\text{ve } R)$$

# 3-5-1 Example 1

Draw B.M.D. S.F.

Solution:-

1- Relative stiffness:-  $K_{AB}: K_{BC}$  1:2.661:2

2- Fixed and Moment:-

$$MF_{BA} = \begin{array}{c} 3 \times 6^2 \\ MF_{BA} = \begin{array}{c} 12 \\ 3 \times 6^2 \end{array} = -9 \ t.m.$$

$$MF_{BA} = +$$
 12  $= +9$ ,  $MF_{BC} = +$   $= -18$   
12

 $3 \times 8^2$ MF<sub>CB</sub>=+ 12 =+18 3- Two unknown  $\theta_B + \theta_C$  then two static equations are required. 1)  $\sum M_B = 0$ 

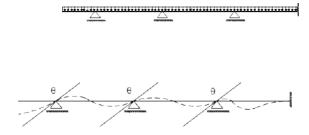
2) 
$$M_{\rm C} = 0$$

Hence:

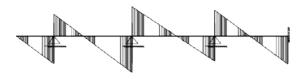
$$M_{BA} + M_{BC} = 0$$
 ..... (1)

But:

 $M_{AB} = -9 + \theta_B$  $M_{BA} = 9 + 1 (2\theta_{B})$  $M_{BC} = -16 + 2 (2\theta_B + \theta_C)$  $M_{CB} = +16 + 2 (2\theta_{C} + \theta_{B})$ From eqns. (1&2) $9 + 2\theta_{\rm B} + (-16 + 2(2\theta_{\rm B} + \theta_{\rm C})) = 0$  $6\theta_B + 2\theta_C$  $= 7 \qquad \dots \dots (3)$ = - 16 and  $4\theta_{\rm C} + 2\theta_{\rm B}$ = - 8.....(4) $2\theta_{\rm C} + \theta_{\rm B}$ from 3 & 4  $5 \theta_{\rm B}$ = 15= 15 = 3.0 $\theta_{\rm B}$ 5 = - 5.5  $\theta_{\rm C}$ 1.e.  $M_{AB} = -9 + 3.4 = 5.6$ t.m  $M_{BA} = 9 + 23.4 = 15.8 \text{ t.m}$  $M_{BC}$  = - 18 + 2 (2 3.4) + (- 5.5) = - 15.0 t.m  $M_{CB} = 16 + 2 (2.3 - 5.7 + 3.4) = 0.0 (0.k)$ 







1- **<u>Unknowns</u>**  $\theta_A$  ,  $\theta_B$  , &  $\theta_C$ 

# 2- Fixed end Moment

$$MF_{AB} = MF_{BC} = MF_{CD} = \begin{pmatrix} 2 \times \\ 6^2 \\ 12 \end{pmatrix} = -6 \text{ t.m. etc}$$

#### 3- Condition eqns.

 $M_{\rm AB}$  = - 4 t.m,  $M_{\rm BA}+M_{\rm BC}$  = 0, &  $M_{\rm CB}+M_{\rm CD}$  = 0

#### 4- Slope deflection equations

$M_{AB} = -6 + (2\theta_A + \theta_B) = -4$		
$2\theta_A+\theta_B$	= 2(1)	
$M_{BA} + M_{BC} \\$	= 0	
$+ 6 + (2\theta_{\rm B} + \theta_{\rm A}) - 6 + ($	$2\theta_{\rm B} + \theta_{\rm C}) = 0$	
$4\theta_B+\theta_A+\theta_C$	= 0 (2)	
$M_{CB}\ +\ M_{CD}$	= 0	
$= 6 + 2\theta_{\rm C} + \theta_{\rm B} - 6 + 2\theta_{\rm C}$	$\Theta_{\rm C} = 0$	
$4 \theta_C + \theta_B$	= 0(3)	

From eqn.3 
$$\theta_{\rm C} = -\theta_{\rm B}_4$$

Substitute in eqn. (2)

Hence:	3.75	$\theta_{\rm B} + \theta_{\rm A} = 0(2)$
	$0.5\theta_B+\theta_A$	= 1 (2)
	$3.25\theta_B$	= - 1
	$\theta_{\rm B}$	= - 1
	$\theta_{\rm A}$	= 1.15
	$\theta_{\rm C}$	= 0.077

Hence:

Mab	= -6 + 2x1.15 + (307)			
	= - 4 t.m	0.K		
Мва	= 6 + 2x (307) +	1.15	= 6.536	t.m
Мсв	= 6 + 2x .77 + (3)	607)	= 5.85	t.m
Mdc	= 6 + .077		= 6.077	t.m

# Solution:-

1- Unknown displacements are $\theta_B \& \theta_D$			
2- Equations of equilibrium are:-			
$M_{DB} = 0$	(1)		
$M_{BA} + M_{BD} + M_{BC} = 0.$	(2)		
3- Relative Stiffness:-			

 $K_{\rm AB}{:}\;K_{\rm BC}{:}\;K_{\rm BD}{\,=\,}35{:}31.\;5{:}22$  ; 51. 56:1. 4:1.0.

4- Fixed and Moments:

$$= -9 \times 6 \times 3 \times 3 = -6$$
$$MF_{AB} \qquad t.m$$

$$MF_{BA} = 9 \times \underbrace{6 \times 3}_{9 \times 9} \times 6 = 12 \\ -3 \times 7^2 \quad t.m$$

$$MF_{BD} = 12 = -12.25 \ t.m$$
$$MF_{DB} = \frac{-3\times}{12} = -12.25 \ t.m$$

From the equations 1 & 2 hence;

$$\begin{split} M_{DB} &= MF_{DB} + (2\theta_D + \theta_B) \\ &= 12.25 + 1 (2\theta_D + \theta_B) = 0 \\ &2\theta_D + \theta_B + 12.25 = 0 - - - - (3) \end{split}$$
 and 
$$\begin{split} M_{BA} &= 12 + 1.56 (2\theta_B) \\ M_{BD} &= 12.25 + 1.0 (2\theta_B + \theta_D) \\ M_{BC} &= 0 + 1.4 (2\theta_B + 0) \\ i.e. \\ 12 + 1.56 (2\theta_B) - 12.25 + 2\theta_B + \theta_D + 1.4 (2\theta_B) = 0 \\ &7.92\theta_B + \theta_D - .25 = 0 - - - - (4) \\ &0.5\theta_B + \theta_D + 6.125 = 0 - - - (3) \\ i.e &7.42 \theta_B - 6.375 = 0 \\ &\theta_B = 0.86 \\ &\theta_D = - 6.55 \end{split}$$

Hence:

 $M_{BA} = 12 + 1.56 \; (2 \times .86) = 14.68 \; t.m$ 

$$\begin{split} M_{BD} &= -12.25 + (2 \times .86 - 6.55 \times 1) &= -17.08 \\ M_{BC} &= 1.4 \; (2 \times .86) &= 2.41 \\ M_{DB} &= 12.25 + (2 \times -6.55) &= zero \end{split}$$

1 MBC	= 1.205
$M_{CB} = 2$	

 $M_{AB} = -6 + 1.56 \; (.86) \qquad \qquad = -4.66$ 

# <u>Two equilibrium eqns.</u>

$M_{AB} + M_{AA} \\$	= 0	(1)
$M_{BB} + M_{BA} +$	4= 0	(2)

# **Slope deflection eqns.**

 $M_{AB} = o + 1.6 (2\theta_A + \theta_B)$ 

$$M_{AA} = \begin{array}{cc} -10 & +(2\theta & +\theta A) \\ \times 16 & A \\ 8 \end{array}$$

$$M_{AA} = -20 + \theta_A$$
  

$$M_{BA} = 0 + 1.6 (2\theta_B + \theta_A)$$
  

$$M_{BB} = -42.67 + (2\theta_B + \theta_B)$$
  

$$= -42.67 + \theta_B$$

Hence:

$$3.2\theta_{A} + 1.6\theta_{B} + \theta_{A} - 20 = o$$

$$4.2\theta_{A} + 1.6\theta_{B} = 20.....(1)$$

$$-42.67 + 4.2 \theta_{B} + 1.6\theta_{A} + 4 = 0$$

$$1.6\theta_{A} + 4.2\theta_{B} = 38.67....(2)$$

$$1.6\theta_{A} + 0.61\theta_{B} = 7.62....(1)$$

3.59θ <sub>B</sub>	= 31.05
$\theta_{\rm B}$	= 8.65
$\theta_{\rm A}$	= 1.46
M <sub>AB</sub>	= -18.52

$M_{BA}$	= 30
$M_{BB}$	= - 34

Example 5

Draw B.M.D for the shown frame

Solution:-

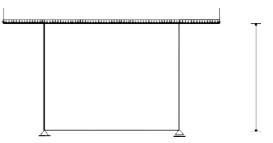
#### - Two condition equations.

$$\begin{split} M_{AA} + M_{AB} &= 0.....(1) \\ M_{BA} + M_{BB} + 8 &= 0.....(2) \end{split}$$

- Relative stiffness 1:  $\frac{1}{10} = 1:1.6$ 

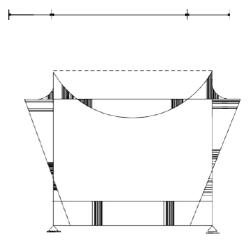
- Slope deflection equations:

$$\begin{split} M_{AA} &= (2\theta_A - \theta_A) = \theta_A \\ M_{AB} &= (2\theta_A - \theta_B) \times 1.6 \\ M_{BA} &= (2\theta_B - \theta_A) \times \theta_A \end{split}$$



 $M_{BB} = 42.67 + (2\theta_B - \theta_B)$ 

-



Hence:

$$\begin{split} \theta_{A} + 3.2\theta_{A} + 1.6V_{B} &= 0 \\ 4.2\theta_{A} + 1.6\theta_{B} &= 0 \ \dots \ (1) \end{split}$$

$$3.2\theta_{\rm B} + 1.6\theta_{\rm A} + \theta_{\rm B} - 42.67 + 8 = 0$$

 $4.2\theta_{\rm B} + 1.6\theta_{\rm A} = 34.67...(2)$ 

## Example 6:

- Draw B.M.D for the given structure.

## **Solution:**- once statically indeterminate.

1- Fixed end moments

 $MF_{AB} = - \begin{array}{c} 8 \times 20 \\ 8 & = -20 \ t.m \end{array}$  $MF_{BA} = - \begin{array}{c} 8 \times 20 \\ 8 & = -20 \ t.m \end{array}$  $MF_{BC} = - \begin{array}{c} 4 \times 10 \\ 8 & = -5 \ t.m \end{array}$ 

$MF_{CB} = -$	$10 \times 8 = -10$ t.m 8
MF <sub>DB</sub>	= 10  t.m

2- <u>From Static:-</u>  $\sum M_B = o$ 

$M_{BA} + M_{BC} + M_{BD} = 0$	
$M_{BA} = MF_{BA} + (2\theta_B)$	
$M_{BA} = 20 + 2\theta_B$	 (1)
$M_{BC} = \textbf{-} 5 + 2\theta_B$	 (2)
$M_{BD} = -10 + 2\theta_B$	 (3)

Hence:  $5 + 6\theta_B = o$  $\theta_B = -o.833$ 

## Hence:

$M_{BA} = 18.34 \text{ t.m}$ , MBC = -6	5.67, MBD = -11.67	t.m
$M_{AB} = -20$	= - 20.833 t.m	
$M_{CB} = 5 + \theta B$	= - 4.167	t.m
$M_{DB} = 10 + \theta B$	= 9.167	t.m

Example 7:

Draw B.M.D for the shown frame

#### Solution:

" 3 time statically ind."  $\theta_A$  ,  $\theta_B$  , &  $\theta_C$ 

### 1- Fixed end moments:

 $MF_{AB} = -10$  $MF_{BA} = +10$  $MF_{BC} = -25$ 

 $MF_{CD} = MF_{DC} = zero$ 

#### 2- <u>Relative Stiffness</u> 1:1:1

$M_{AB}$	= 0	(1)
$M_{BA} + M_{BC}$	g = 0	(2)
$M_{CB} + M_{CD}$	, = 0	(3)

Equs.

$M_{AB}$	$= -10 + (2\theta_A + \theta_B)$
$M_{BA}$	$= 10 + (2\theta_B + \theta_A)$
$M_{BC}$	$= -25 + 2\theta_B + \theta_C$
Mcb	$= 25 + 2\theta_C + \theta_B$
Mcd	$= 2\theta_{\rm C}$
M <sub>DC</sub>	$= \theta_{C}$

From 1,2 & 3

$2\theta_A+\theta_B$	= 10	(1)
$4\theta_{\rm B} + \theta_{\rm A} + \theta_{\rm C}$	= 15	(2)
$4\theta_C + \theta_B$	= - 25	(3)

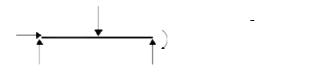
By solving the three eqns. hence;

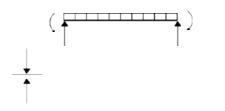
 $\theta_A = 2.5 \qquad \qquad \theta_B = 5 \qquad \qquad \theta_C = -7.5$ 

Substitute in eqns of moments hence;

Мав	= - 10 + 5	= zero (o.k)
Mba	= 10 + 10 + 2.5	= 22.5 t.m
Мвс	= - 25 + 10 - 7.5	= - 22.5 t.m
Мсв	= 25 - 15 + 5	= 15 t.m

M <sub>CD</sub>	= - 15	t.m
M <sub>DC</sub>	= - 7.5	t.m





## 3-6 Frames with Translation

Examples to frames with a single degree of freedom in translation.

Example 8:

Draw B.M.D for the shown frame.

1- Unknowns:  $\theta B$ ,  $\theta C$ ,  $\Delta$ 

#### 2- Relative stiffness

KAB: KBA: KCD 1:2:1.5 4:8:6 1:1:1

#### 3- Fixed end moments

 $MF_{AB} = o M_{BA} = o$   $MF_{BC} = MCB = zero$   $MF_{CD} = -6 t.m$  $MF_{DC} = +6 t.m$ 

# 4- From Statics the equilibrium eqns

$M_{BA} + M_{BC} = 0$	(1)
$M_{CB} + M_{CD} = 0$	(2)

# 5- Shear equation (In direction of X, $\sum x = 0$ )

$$6 + X_A + X_D - 8 = o$$

hence X + MBA + MAB and xD = MCD + MDC + 44 **6-** Slope deflection eqns:

$$M_{BA} - 0 + 1 (2\theta_B - 3 \frac{\Delta}{4}), M_{AB} = 0 + 1 (\theta_B - 3 \frac{\Delta}{4})$$

$$M_{BC} = 0 + 1 (2\theta_B + \theta_C)$$
Hence: 
$$4\theta_B - 0.75\Delta + \theta_C = 0$$

$$M_{CB} = 0 + 1 (2\theta_C + \theta_B)$$
(1)

$$M_{CD} = -6 + 1 (2\theta_C - 3 \frac{\Delta}{6}),$$

$$M_{DC} = + \ 6 + 1 \ (\theta_C \text{--} 3 \ \underline{\Delta})$$

Hence:

$$1 \Delta = 6 \tag{2}$$

$$2 + (2\theta_B - .75 \Delta) + (1\theta_B - .75 \Delta) + (-6 + 2\theta_C - \Delta) + (6 \Delta = 0 \Delta =$$

 $2 + 0.75 \,\theta_B$  - .375  $\Delta + \frac{1}{2} \theta_C - 0.1667 \Delta = o$ 

$$\theta_{\rm B} + .67 \ \theta_{\rm C} - 072\Delta = -2.66$$
(3)  
**Subtract (3) from (2)**  
 $3.33 \ \theta_1 + 0.288 \ \Delta = 8.33$   
 $\theta_{\rm C} - 0.067 \ \Delta = 2.6$ (4)  
**Subtract (1) from (2) × (4)**  
 $15 \ \theta_{\rm C} - 1.25 \ \Delta = 24$   
 $\theta_{\rm C} - 0.08 \ \Delta = 1.6$ (5)  
**From (4) & (5)**  $0.147\Delta = 1$   
 $\Delta = 6.80$   
 $\theta_{\rm C} = 2.149$ 

 $\theta_B = 0.799$ 

$$\begin{split} M_{BA} &= -3.5 \text{ t.m} \qquad, M_{AB} = -4.301 \text{ t.m}, \ M_{BC} = 3.79 \\ M_{CB} &= 5.1 \text{ t.m} \qquad, M_{CD} = -5.1 \text{ t.m} \quad, \qquad M_{DC} = 4.744 \end{split}$$

### Example 9:-

Write the shear & condition eqns for the following frame.

### Solution:-

Three unknowns:  $\theta B, \theta C, \Delta$ 

### **Condition equations:**

$M_{BA} + M_{BC} = o \qquad ($	[1)
--------------------------------	-----

 $M_{CB} + M_{CD} = o \qquad (2)$ 

#### Shear eqn.

$$X_{A} + X_{B} + P1 + P2 = o$$

$$\begin{pmatrix} -P1 + M_{AB} + M_{BA} \end{pmatrix} + \begin{pmatrix} M_{CD} + M_{DC} \end{pmatrix} P1 + P2 = o$$

$$\begin{pmatrix} 3 \end{pmatrix}$$

#### Example 10:

Find the B.M.D for the shown structure.

# Solution:-

$$\theta_{\rm D} = \theta_{\rm E} = \mathbf{o}$$
$$\theta_{\rm C} = -\theta_{\rm C}$$
$$\theta_{\rm B} = -\theta_{\rm B}$$

1- Unknown displacements are:

### 2- Relative Stiffness:

AB : BE : BC : CD : ED

$$\frac{1}{2}:\frac{2}{3}:\frac{1}{2}:\frac{1}{2}:\frac{1}{3}:\frac{1}$$

### 3- Fixed end moment:-

 $MF_{BE} = - \frac{4 \times 36}{12} = -12 \text{ t.m}$ 

 $MF_{EB} = +12 \text{ t.m}$ 

 $MF_{CD} = \begin{array}{c} 1.5 \times 36 \\ 12 & = -4.5 \text{ t.m} \end{array}$ 

 $MF_{DC} = +4.5$ 

### 4- Equilibrium equations:-

- 1-  $M_{CD} + M_{CB} = o$
- 2-  $M_{BC} + M_{BA} + M_{BE} = o$
- 3- Shear condition:(33–16.5)+  $\frac{M_{CD} + M_{DC}}{6} + \frac{M_{DE} + M_{ED}}{6}$

$$M_{CD} = -4.5 + 5 (2\theta_{C} + \theta_{D} - 3R)$$
  

$$M_{CB} = 0 \ 3 (2\theta_{C} + \theta_{B})$$
  

$$M_{BC} = 0 + 3 (2\theta_{B} + \theta_{C})$$
  

$$M_{BA} = 0 + 3 (2\theta_{B})$$
  

$$M_{BE} = -12 + 10 (2\theta_{B} - 3R)$$

### Hence

$$-4.5 + 10 \theta_{\rm C} - 15 R + 6 \theta_{\rm C} + 3 \theta_{\rm B} = 0$$
  
$$16\theta_{\rm C} + 3\theta_{\rm B} - 15R - 4.5 = 0$$
(1)

# And

$$16\theta_{\rm B} + 3\theta_{\rm C} + 6\theta_{\rm B} - 12 + \theta_{\rm B} - 3\theta_{\rm R} = 0$$
  
$$3\theta_{\rm C} + 32\theta_{\rm B} - 30R - 12 = 0$$
 (2)

and

16.5(	$\frac{-30R+30}{6}$	$\theta_B - 60R$ ) = 0.6
$15\theta c$		

 $2.5 \theta_{C} + 5\theta_{C} + 17R + 16.5 = 0 \qquad (3)$ by solving equation 1,2 & 3 get  $M_{AB} = + 6.66 \text{ t.m}$  $M_{BA} = + 13.32 \text{ t.m}$  $M_{BC} = + 19.0 \text{ t.m}$  $M_{CB} = + 18 \text{ t.m } M_{BE}$  $= - 32.32 \text{ t.m } M_{EB} = 30.53 \text{ t.m } M_{CD} = 18 \text{ t.m } M_{DC} = -$ 18.43 t.m

# 3-7 <u>Frame with multiple degree of freedom in translation.</u> <u>Example 11</u>:

Write the shown equations and condition eqns for the given frame.

## <u>Solution</u>

**<u>Unknowns:</u>**  $\theta B, \theta C, \theta D, \theta E, \Delta 1, \Delta 1$ 

### **Condition eqns**

 $M_{BE} + M_{BA} + M_{BC} = 0 \quad (1)$   $M_{CB} + M_{CD} = 0 \quad (2)$   $M_{DC} + M_{DE} = 0 \quad (3)$   $M_{EB} + M_{EF} + M_{ED} = 0 \quad (4)$ 

#### **Shear eqns :**

Equilibrium of the two stories.

#### <u>At sec (1) – (1) :-</u>

(Level CD)

 $\mathbf{P}_2 + \mathbf{X}_c + \mathbf{X}_E = \mathbf{0}$ 

$$\begin{array}{ccc} M & + M_{BC} & + M_{DE} & + M_{ED} = 0 \\ \mathbf{P}_2 + & {}^{CB} \end{array}$$

h2

<u>At sec. (2) – (2):-</u>

(Level BE) or  $\sum x = 0$  $P_1 + P_2 + x_A + x_F = 0$ 

h2

$$M_{BA} + M_{AB} + M_{EF} + M_{FE} = 0$$

*hh*1

# Example 12:-

Draw B.M.D for the given structure.

olution:-

S

# 1- <u>Relative Stiffness:-</u>

# 2- Equilibrium equations:-

$$M_{AB} + M_{AC} = 0 \qquad (1)$$

- $M_{BA}+M_{BD} \qquad = 0 \qquad (2)$
- $M_{CA} + M_{CD} + M_{CE} = 0$  (3)

$$M_{DB} + M_{DF} + M_{DC} = 0$$
 (4)

 $\Sigma x = 0$  at Level A-B

$$2 + (6-3) + \frac{M_{AC} + M_{CA} + M_{BD} + M_{DB}}{6} = 0 (5)$$

 $\Sigma x = 0$  at Level CD

$$11 + \frac{M_{CE} + M_{EC} + M_{DF} + M_{FD}}{6} = 0 (6)$$

$$\begin{split} M_{AB} &= -8 + 1 \, \left( 2 \theta_A + \theta_B \right) M_{AC} \\ &= 3 + \left( 2 \theta_A + \theta_C - 3 R_1 \right) \\ M_{AC} &= -3 + \left( 2 \theta_C + \theta_A - 3 R_1 \right) \end{split}$$

 $M_{CA} = 16 + (2\theta_B + \theta_A)$ 

->

$$\begin{split} M_{BD} &= 0 + (2\theta_B + \theta_D - 3R_1) \\ M_{DB} &= 0 + (2\theta_D + \theta_B - 3R_1) \\ M_{DF} &= 0 + (2\theta_D + 0 - 3R_2) \\ M_{FD} &= 0 + (\theta_D - 3R_2) \\ M_{CD} &= -48 + 2 (2\theta_C + \theta_C) \\ M_{CD} &= +48 + 2 (2\theta_D + \theta_C) \\ M_{CE} &= -8 + (2\theta_C - 3R_2) \\ M_{EC} &= + (\theta_C - 3R_2) \end{split}$$

3- Fixed end moment:-

$$MF_{AB} = \frac{-9 \times 4 \times 8 \times 4 = -8 \text{ t.m}}{12 \times 12}$$

 $MF = -9 \times 8^2 \times 4 = + \qquad t.m$ 

ва 12 2 16

 $1 \times 6^2 = +3 t.m$ MF<sub>AC</sub> = 12  $MF = 1 \times 6^2 = - t.m$ 

$$MF_{CD} = \begin{array}{c} 12 & 3 \\ 4 \times 12 & -48 \\ 12 & -48 \end{array} t.m$$

 $MF_{DC} = +48 \quad t.m$ 

4- <u>Unknown displacement:</u>

 $\theta A$  ,  $\theta B$  ,  $\theta C$  ,  $\theta D$  ,  $\Delta_1$  ,  $\Delta_2$ 

by Solving the six equations one can get;

Мав	= - 3.84	t.m
Мва	=+18.39	t.m
Mac	= 3.84	t.m
Mca	=+7.29	t.m
Mbd	= - 18.39	t.m
Mdb	= - 22.97	t.m
Mcd	= - 11.15	t.m
Mdc	= - 53.44	t.m
Mce	= 3.87	t.m
Mec	= - 13.44	t.m
Mdf	= - 30.47	t.m
Mfd	= - 26.15	t.m

**Example (13):-**

Write the shear equations & equilibrium equations for the shown frame.

Solution:

Shear eqns:

 $X_{CE} + X_{BA} + P_1 = 0....(1)$ 

$$M_{EC} + M_{CE} + M_{AB} + M_{BA} + \mathbf{P}_1 = \mathbf{o}$$

 $x_D + x_G + x_E + P_2 = 0 --- (2)$ 

$$\begin{array}{cccc} M_{DE} + M_{ED} & + M_{GF} & + M_{FG} & - M_{EC} + M_{CE} \\ h_2 & h_2 & h_1 & + P_2 = 0 \end{array}$$

Or:

 $X_A + X_D + X_G + P_1 + P_2 = 0$ 

$$\begin{array}{c} +M {}_{DE} + M {}_{ED} + M {}_{GF} \\ M {}_{AB} & h_2 \\ h_1 + h_2 & h_2 \end{array} + M {}_{FG} + \mathbf{P}_1 + \mathbf{P}_2 = \mathbf{0} \\ h_2 \end{array}$$

Example 14:-

- a- Write the equations of equilibrium including the shear equations for the frame.
- b- Write the slope deflection equations in matrix for members CE & GH.
- c- By using the slope deflection method; sketch elastic curve.
- d- Sketch your expected B.M.D

### Solution:-

(**Unknowns** =  $\theta_{C}$ ,  $\theta_{D}$ ,  $\theta_{E}$ ,  $\theta_{F}$ ,  $\theta_{G}$ ,  $\theta_{A}+\theta_{K}$ ,  $\theta_{L}$ ,  $\Delta_{1}$ ,

$$\Delta_2, \Delta_3, \quad \Delta_4$$

Relative stiffness: 1:1

a- equilibrium equations

$M_{KL} + M_{KG} = 0 \qquad (1)$	$M_{KL} + M_{KG}$	= 0	(1)
----------------------------------	-------------------	-----	-----

- $M_{LK} + M_{LH} = 0 \qquad (2)$
- $M_{GK} + M_{GH} + M_{GE} = 0$  (3)
- $M_{HG} + M_{HL} + M_{HF} = 0 \tag{4}$
- $M_{EG} + M_{EC} + M_{FF} = 0$  (5)
- $M_{FE} + M_{FD} + M_{FH} = 0$  (6)
- $M_{CE} + M_{CD} + M_{CA} = 0$  (7)
- $M_{DC} + M_{DB} + M_{DF} = 0$  (8)

Shear equations:-

a- at Level GH

$$5 + 10 + (X_G - 5) + X_H = 0 \tag{9}$$

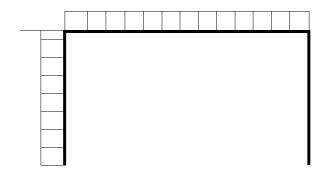
$$X_{\rm G} = \frac{M_{\rm GK} + M_{\rm KG}}{5}$$

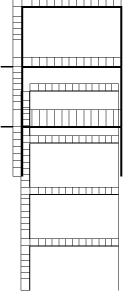
$$X_{\rm H} = \frac{M_{\rm HL} + M_{\rm LH}}{5}$$

b- at Level EF  $5 + 10 + 20 + (X_E - 5) + X_F = 0$  $30 + X_E + X_F = 0$  (10)

$$M_{EG} + M_{GE}$$
$$X_{E} = 5$$

$$M_{FH} + M_{HF}$$
$$X_{F} = 5$$





c- at Level CD  

$$5 + 10 + 10 + 30 + (X_C - 5) + X_D = 0$$
  
 $50 + X_C + X_D = 0$ .....(11)

$$X_{C} = \begin{matrix} M & c_{E} + M_{EC} \\ 5 \\ M_{DF} + M_{FD} \\ X_{D} = \begin{matrix} 5 \end{matrix}$$

d- at Sec AB:- $5 + 10 + 10 + 10 + 40 + (X_A - 5) + X_B = 0$ 

$$70 + X_A + X_B$$

= 0 .....(12)

$$X_{A} = \begin{array}{c} M_{AC} + M_{CA} \\ X_{A} = 5 \end{array}$$

$$X_{\rm B} = \begin{array}{c} M & + M_{\rm EC} \\ CE & 5 \end{array}$$

# 3-8 <u>Slope deflection eqns in matrix form:</u>

## 1- Member CE

$$M_{CD} = MF_{CE} + \frac{2EI}{5} \left( 2\theta_C + \theta_E - 3 \quad \Delta^2 - \frac{1}{5} \Delta^1 \right)$$
$$M_{EC} = MF_{EC} + \frac{2EI}{5} \left( 2\theta_E + \theta_C - 3 \quad \Delta^2 - \frac{1}{5} \Delta^1 \right)$$

 $2 \times 5^2$ MF<sub>CE</sub> = - 12 = -4.16 t.m

$MF_{EC} = +4.16  t.n$
------------------------

In Matrix form:

MCE	- 4.16		2	1-3	$\theta_{C}$
=		+ 2EI 5			$\theta_{\rm E}$
MEC	4.16		1	2-3	$R_2$

$$\mathbf{R}_2 = \begin{array}{c} \Delta_2 - \Delta_1 \\ \mathbf{R}_2 = \begin{array}{c} 5 \end{array}$$

### 2- member GH

Мдн	- 16.67	2	1	$\theta_G$
=	+ 26I			
Mhg	+ 16.67	1	2	$\theta_{\rm H}$

#### d-B.M.D

Example 15:-

By using slope deflection method;

1- Draw B.M.D for the shown frame.

2- Sketch elastic curve.

Solution:

- 1- Relative stiffness 1:1
- 2- unknowns:  $\theta_B = -\theta_B$  (From symmetry)
- 3- Equilibrium eqns

 $M_{BA} + M_{BC} + M_{BD} + M_{BB} = o \qquad (1)$ 

4-Fixed end moments

	$4 \times 6_2$	
MFAB	12	= <b>-</b> 12 t.m
=		

$$\label{eq:mfba} \begin{split} MF_{BA} &= = + 12 \\ MF_{BC} &= MF_{CB} = MF_{BD} = MF_{DE} = o \end{split}$$

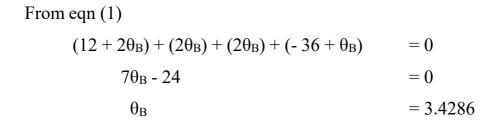
 $MF_{BB} = - \frac{2 \times 12}{2} - \frac{8 \times 12}{8} = -36 \text{ t.m}$ 

## 4- Slope deflection eqns

 $M_{AB}$  = - 12 +( $\theta B$ )

 $M_{BA} = 12 + 2\theta B$ 

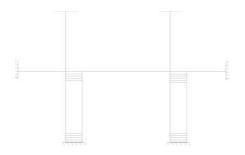
 $\begin{array}{ll} M_{BC} &= 2\theta B \\ M_{BD} &= 2\theta B \\ M_{BB} &= -36 + \theta B \\ M_{CB} &= \theta B \\ M_{DB} &= \theta B \end{array}$ 



hence

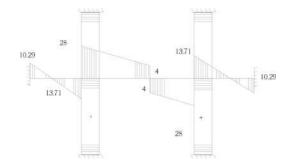
$M_{AB} = -$	8.57	t.m
$M_{BA} =$	18.86	t.m
$M_{BC} =$	6.86	t.m
$M_{BB} = -$	32.58	t.m
$M_{CB} =$	3.428	t.m

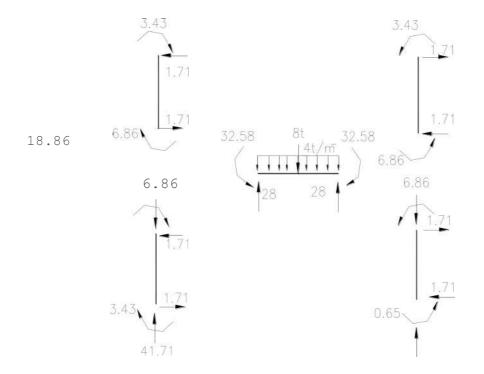
 $M_{DB} = 3.428$  t.m  $M_{BD} = 6.86$ 



41.11 41.71

1.71 1.71





## The Free Body Diagram to find the S. F. & N. F. <u>SHEET (3)</u>

1) Draw S.F.D. and B.M.D. for the statically indeterminate beams shown in figs. From 1 to 10.

2) Draw N.F.D., S.F.D. for the statically indeterminate frames shown in figs. 11 to 17. Using matrix approach 1.

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..... 1